



## **GRL Platform Solutions**

**PCI Express® 6.0 Base Receiver Test Method of  
Implementation (MOI)  
for Anritsu 64Gbps Physical Layer Test Suite  
Using Anritsu MP1900A BERT,  
High Performance Real-Time Oscilloscope,  
and GRL-PXE6-BASE-RXA Calibration and Test Software**



*Published on 17 July 2026*

## DISCLAIMER

This document is provided “as is” with no warranties whatsoever, including any warranty of merchantability, no infringement, fitness for any particular purpose, or any warranty otherwise arising out of any proposal, specification, or sample. The GRL Platform Solutions disclaims all liability for infringement of proprietary rights, relating to use of information in this specification. No license, express or implied, by estoppel or otherwise, to any intellectual property rights is granted herein.

All product names are trademarks, registered trademarks, or service marks of their respective owners.



Copyright © 2026 GRL Platform Solutions. All rights reserved.

## TABLE OF CONTENTS

|          |                                                                                   |           |
|----------|-----------------------------------------------------------------------------------|-----------|
| <b>1</b> | <b>INTRODUCTION</b>                                                               | <b>7</b>  |
| <b>2</b> | <b>RESOURCE REQUIREMENTS</b>                                                      | <b>8</b>  |
| 2.1      | EQUIPMENT REQUIREMENTS .....                                                      | 8         |
| 2.2      | SOFTWARE REQUIREMENTS .....                                                       | 9         |
| <b>3</b> | <b>SETTING UP GRL-PXE6-BASE-RXA SOFTWARE</b>                                      | <b>10</b> |
| 3.1      | DOWNLOAD GRL-PXE6-BASE-RXA SOFTWARE.....                                          | 10        |
| 3.2      | LAUNCH AND SET UP SOFTWARE.....                                                   | 10        |
| 3.2.1    | Connection Configuration .....                                                    | 12        |
| 3.2.2    | Launch and Set Up GRL-PXE6-BASE-RXA Software (on the Scope or Controller PC)..... | 12        |
| 3.3      | CONFIGURING THE GRL-PXE6-BASE-RXA SOFTWARE BEFORE CALIBRATION .....               | 13        |
| 3.3.1    | Enter Test Session Information.....                                               | 13        |
| 3.3.2    | Set Measurement Conditions.....                                                   | 14        |
| 3.3.3    | Set Up Measurement Requirements.....                                              | 14        |
| <b>4</b> | <b>CALIBRATING USING GRL-PXE6-BASE-RXA SOFTWARE</b>                               | <b>19</b> |
| 4.1      | CALIBRATION FOR TP1 (OUTPUT OF BERT GENERATOR) .....                              | 20        |
| 4.1.1    | Setup for TP1 Calibration .....                                                   | 20        |
| 4.1.2    | Select Calibration.....                                                           | 21        |
| 4.1.3    | Configure Calibration Parameters .....                                            | 23        |
| 4.1.4    | Run Calibration at TP1.....                                                       | 25        |
| 4.2      | CALIBRATION FOR TP2 (OUTPUT OF LONG CHANNEL).....                                 | 26        |
| 4.2.1    | Setup for TP2 Calibration .....                                                   | 26        |
| 4.2.2    | Run Calibration Steps at TP2.....                                                 | 28        |
| 4.3      | CONFIGURE CALIBRATION TARGET VALUES.....                                          | 28        |
| <b>5</b> | <b>TESTING USING GRL-PXE6-BASE-RXA SOFTWARE</b>                                   | <b>30</b> |
| 5.1      | RECEIVER DUT COMPLIANCE TEST SETUP.....                                           | 30        |
| 5.1.1    | Test Setup .....                                                                  | 30        |
| 5.1.2    | Receiver Compliance Tests .....                                                   | 32        |
| 5.1.3    | Receiver Margin Tests .....                                                       | 33        |
| 5.1.4    | Configure Receiver Test Parameters .....                                          | 33        |
| 5.1.5    | Apply Calibrated Values for Testing .....                                         | 33        |
| 5.2      | ENABLE LOOPBACK BER TEST .....                                                    | 34        |
| <b>6</b> | <b>INTERPRETING TEST REPORT</b>                                                   | <b>35</b> |
| 6.1      | DUT INFORMATION.....                                                              | 35        |
| 6.2      | SUMMARY TABLE.....                                                                | 36        |
| 6.3      | CALIBRATION/TEST RESULTS .....                                                    | 37        |
| <b>7</b> | <b>SAVING AND LOADING TEST SESSIONS</b>                                           | <b>39</b> |

## **8 APPENDIX A: METHOD OF IMPLEMENTATION (MOI) USING AUTOMATION 40**

|       |                                                                  |    |
|-------|------------------------------------------------------------------|----|
| 8.1   | PERFORM CALIBRATION AT TP1.....                                  | 40 |
| 8.1.1 | Pre-shoot Calibration .....                                      | 40 |
| 8.1.2 | De-emphasis Calibration .....                                    | 40 |
| 8.1.3 | Launch Amplitude Calibration .....                               | 41 |
| 8.1.4 | RJ Calibration .....                                             | 41 |
| 8.1.5 | SJ Calibration.....                                              | 42 |
| 8.1.6 | SJ Tone Calibration.....                                         | 42 |
| 8.2   | PERFORM CALIBRATION AT TP2 .....                                 | 43 |
| 8.2.1 | ISI Calibration (CEM Connector Channel + Replica Channel) .....  | 43 |
| 8.2.2 | Common Mode (CM) Sinusoidal Interference Calibration .....       | 43 |
| 8.2.3 | Differential Mode (DM) Sinusoidal Interference Calibration ..... | 44 |
| 8.2.4 | Stress Jitter Voltage Eye Calibration .....                      | 44 |

## **9 APPENDIX B: CONNECTING KEYSIGHT OSCILLOSCOPE TO PC 46**

## **10 APPENDIX C: CONNECTING TEKTRONIX OSCILLOSCOPE TO PC48**

## List of Figures

|                                                                                          |    |
|------------------------------------------------------------------------------------------|----|
| Figure 1. Select and Launch GRL Platform Solutions Framework .....                       | 10 |
| Figure 2. Launch PCIe 6.0 Base Rx Test Application.....                                  | 11 |
| Figure 3. See License Details.....                                                       | 11 |
| Figure 4. Check License for Installed Applications .....                                 | 11 |
| Figure 5. Connect Instruments with GRL-PXE6-BASE-RXA Software .....                      | 13 |
| Figure 6. Session Info Page .....                                                        | 13 |
| Figure 7. Select SJ Frequencies.....                                                     | 14 |
| Figure 8. User SJ Frequencies Setting.....                                               | 14 |
| Figure 9. Rx Package Settings.....                                                       | 15 |
| Figure 10. Seasim Settings .....                                                         | 15 |
| Figure 11. DM and CM Calibration Settings.....                                           | 15 |
| Figure 12. SSC and Refclk Setup.....                                                     | 16 |
| Figure 13. Connection Setup .....                                                        | 16 |
| Figure 14. Preset Settings.....                                                          | 16 |
| Figure 15. BER Loopback Test Method.....                                                 | 17 |
| Figure 16. Loopback Mode Setup .....                                                     | 17 |
| Figure 17. BER Test Setup.....                                                           | 17 |
| Figure 18. Compliance BER, Gating Time and Maximum Errors Setup.....                     | 18 |
| Figure 19. Margin Search Parameters Setup .....                                          | 18 |
| Figure 20. Rx Calibration/Test Schematic Overview from the PCIe 6.0 Base Specification   | 19 |
| Figure 21. Calibration Channel IL Limits from the PCIe 6.0 Base Specification.....       | 19 |
| Figure 22. Typical Setup for TP1 Calibration .....                                       | 20 |
| Figure 23. Recommended Setup for TP1 Calibration Using Tektronix ATI Scope .....         | 20 |
| Figure 24. Calibration Selection .....                                                   | 22 |
| Figure 25. Calibration Parameters Configuration Page .....                               | 23 |
| Figure 26. Run Tests.....                                                                | 25 |
| Figure 27. TP1 Connection Diagram Dialog Example .....                                   | 25 |
| Figure 28. Typical Setup for TP2 Calibration .....                                       | 26 |
| Figure 29. Recommended Setup for TP2 Calibration Using Tektronix ATI Scope.....          | 27 |
| Figure 30. Final Calibrated Stressed Eye Diagram Example.....                            | 28 |
| Figure 31. Calibration Target Overwrite Page.....                                        | 29 |
| Figure 32. Typical Receiver DUT Test Setup .....                                         | 30 |
| Figure 33. Typical Receiver Test Setup for System DUT SRIS Refclk Architecture.....      | 31 |
| Figure 34. Typical Receiver Test Setup for Add-In Card DUT SRIS Refclk Architecture..... | 32 |
| Figure 35. Selecting Receiver Compliance Tests .....                                     | 32 |
| Figure 36. Selecting Receiver Margin Tests.....                                          | 33 |
| Figure 37. Receiver Test Parameters Configuration Page.....                              | 33 |
| Figure 38. Selecting To Apply Calibration Values .....                                   | 33 |
| Figure 39. Report Results Page .....                                                     | 35 |

|                                                                   |    |
|-------------------------------------------------------------------|----|
| Figure 40. DUT Information.....                                   | 35 |
| Figure 41. Summary Table .....                                    | 36 |
| Figure 42. Calibration Results Example.....                       | 38 |
| Figure 43. Saving and Loading Calibration and Test Sessions ..... | 39 |
| Figure 44. De-emphasis Calibration Caltable Graph.....            | 41 |
| Figure 45. Keysight Connection Expert.....                        | 46 |
| Figure 46. Oscilloscope's VISA Address.....                       | 47 |
| Figure 47. OpenChoice Instrument Manager In Start Menu.....       | 48 |
| Figure 48. OpenChoice Instrument Manager Menu .....               | 49 |

# 1 Introduction

This User Guide & MOI describes the procedures for receiver (Rx) calibration and jitter tolerance testing based on the PCIe Base 6.0 (ASIC) Specification (for 64.0 GT/s), using the GRL-PXE6-BASE-RXA PCIe 6.0 Base Specification Receiver Calibration and Test Software to automate the Anritsu BERT Model (MP1900A) and a high-performance real-time oscilloscope to calibrate the stressed eye opening and test receiver conformance and jitter tolerance. The GRL-PXE6-BASE-RXA software uses the Seasim statistical data eye simulator to establish the calibrated test channel DDJ. The final calibrated eye diagram uses the Seasim software to achieve the final stressed eye calibration.

The BERT and appropriate accessories provide the necessary test patterns with jitter, ISI, and crosstalk. Additionally, the BERT is used to add the required transmitter (Tx) equalization. The receiver jitter tolerance test includes various Differential Mode Sinusoidal Interference, minimum transmitter voltage amplitude, and jitter which includes random jitter and a sinusoidal periodic jitter component that is swept across specific frequency intervals.

Once the stressed receiver eye opening has been calibrated, the receiver jitter tolerance and margin testing can then be performed on the device under test (DUT). The BERT is used to transmit a modified compliance pattern to the receiver DUT and monitors that the loopback pattern conforms to a First Bit Error Rate (FBER) of less than  $10^{-6}$ .

In summary, this User Guide & MOI basically describes using the GRL-PXE6-BASE-RXA software to:

1. Calibrate the stressed eye at the receiver of the DUT.
  - This includes calibrating Voltage Swing, Random Jitter (RJ), Sinusoidal Jitter (SJ), Insertion Loss (ISI), Differential Mode Noise, Common Mode Noise, Tx Equalization and Eye Height & Width.
2. Test the receiver using FBER. The receiver path is tested with worst case eye to ensure a FBER of less than  $10^{-6}$  can be achieved.

*Note: Important information detailing method of implementation using automation, oscilloscope and other setup information are included in Appendixes of this document. It is highly recommended to thoroughly review these information prior to performing any testing or data collection.*

The GRL-PXE6-BASE-RXA software is designed to work with the Anritsu BERT as a signal source and error detector for automation of the PCIe 6.0 Base Receiver calibration and testing. Details on how to set up and configure the GRL Platform Solutions software are provided in this document.

## 2 Resource Requirements

### 2.1 Equipment Requirements

TABLE 1. EQUIPMENT REQUIREMENTS – SYSTEMS AND ACCESSORIES

| Equipment                       | Qty. | Description                                                                                                                                                                                                                                                                                                                                                                                                                                      | Key Specification Requirement                        |
|---------------------------------|------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------|
| Keysight/Tektronix Oscilloscope | 1    | High Performance Real-time Oscilloscope <sup>[a]</sup>                                                                                                                                                                                                                                                                                                                                                                                           | ≥ 50 GHz bandwidth with Windows 7+ OS <sup>[b]</sup> |
| Anritsu MP1900A BERT            | 1    | MP1900A Signal Quality Analyzer, with following modules: <ul style="list-style-type: none"> <li>• MU181000A/B 12.5 GHz Synthesizer</li> <li>• MU181500B Jitter Modulation Source</li> <li>• MU196020A 64.2G bit/s or 64.2G baud PAM4 Pulse Pattern Generator <sup>[c]</sup></li> <li>• MU196040B 58.2G bit/s or 58.2G baud PAM4 Error Detector</li> <li>• MU196060A 32G baud NRZ/PAM4 Re-Driver</li> <li>• MU195050A Noise Generator</li> </ul>  |                                                      |
| External Refclk Source          | 1    | Required for Receiver DUT testing in the SRIS (independent Refclk) mode                                                                                                                                                                                                                                                                                                                                                                          |                                                      |
| Computer/PC (laptop or desktop) | 1    | For automation control<br>Minimum requirements: <ul style="list-style-type: none"> <li>• Windows 10+ OS</li> <li>• Intel Core i5 processor</li> <li>• 120GB SSD storage</li> <li>• 16GB RAM</li> <li>• Gigabit Ethernet</li> </ul> Recommended requirements: <ul style="list-style-type: none"> <li>• Windows 10+ OS</li> <li>• Intel Core i7+ processor</li> <li>• 200GB SSD storage</li> <li>• 32GB RAM</li> <li>• Gigabit Ethernet</li> </ul> |                                                      |

<sup>[a]</sup> Oscilloscope with scope software requirements as specified in vendor specific MOI's. For example, when using the Keysight Scope, scope software such as Keysight InfiniiSim / EZ-JIT / Serial Data Analysis / Serial Data Equalization that are required for testing and signal processing must be pre-installed on the Scope. Similarly, the Tektronix Scope shall be used with DPOJET (Jitter and Eye Analysis Tools) software for making measurements.

<sup>[b]</sup> Oscilloscope with scope bandwidth as specified in vendor specific MOI's.

<sup>[c]</sup> The GRL-PXE6-BASE-RXA software supports the PAM4 signal with FEC modulation.

**Note:** Cable connector type and length requirements may vary according to the lab setup and the dimensions of the DUT board. Table below is a recommended list. Please also refer to the respective manufacturer for detailed cabling recommendations related to PCI Express.

TABLE 2. EQUIPMENT REQUIREMENTS – CABLES

| Cable                                                  | Qty.    | Key Specification Requirement                                                            |
|--------------------------------------------------------|---------|------------------------------------------------------------------------------------------|
| Anritsu J1624A SMA-SMA cable                           | 3       | 30cm                                                                                     |
| Anritsu J1625A SMA-SMA cable                           | 4       | 100cm                                                                                    |
| Anritsu J1551A K-K phase matched cable pair            | 3 pairs | 3ft                                                                                      |
| Anritsu J1792A V-K cable set                           | 1       | To connect between MU196020A and MU195050A                                               |
| J1917A coaxial semi-rigid cable                        | 1       | To connect between MU196060A clock output and MU196040B clock input                      |
| J1932A coaxial skew matched cable pair                 | 1       | 0.8m, V connector<br>To connect between MU196060A data outputs and MU196040B data inputs |
| Rosenberger L71-456-102 phase matched SMA-SMP adapters | 2 pairs |                                                                                          |

## 2.2 Software Requirements

TABLE 3. SOFTWARE REQUIREMENTS

| Software                                                     | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |
|--------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| GRL-PXE6-BASE-RXA                                            | GRL Platform Solutions PCIe® 6.0 (64.0 GT/s) Base Specification Receiver Calibration and Test Automation Software – <a href="http://www.grlps.com">www.grlps.com</a><br>Included with Node Locked License to single oscilloscope or PC OS                                                                                                                                                                                                                                                                                                                                         |
| VISA (Virtual Instrument Software Architecture) API Software | VISA Software is required to be installed on the controller PC running GRL-PXE6-BASE-RXA software. GRL Platform Solutions' software framework has been tested to work with all three versions of VISA available on the Market:<br>1. NI-VISA: <a href="http://www.ni.com/download/ni-visa-17.0/6646/en/">http://www.ni.com/download/ni-visa-17.0/6646/en/</a><br>2. Keysight IO Libraries: <a href="http://www.keysight.com">www.keysight.com</a> (Search on IO Libraries)<br>3. Tektronix TekVISA: <a href="http://www.tek.com">www.tek.com</a> (Downloads > Software > TekVISA) |
| Seasim                                                       | Seasim tool for post-process analysis of the captured waveform (Eye Opening simulation software at TP2P) – <a href="http://www.pcisig.com">www.pcisig.com</a>                                                                                                                                                                                                                                                                                                                                                                                                                     |

### 3 Setting Up GRL-PXE6-BASE-RXA Software

This section provides the procedures to start up and pre-configure the GRL-PXE6-BASE-RXA automation software before running tests. It also helps users familiarize themselves with the basic operation of the software.

*Note: The GRL Platform Solutions software installer will automatically create shortcuts in the Desktop and Start Menu when installing the software.*

To start using the GRL Platform Solutions software, follow the procedures in the following sections.

#### 3.1 Download GRL-PXE6-BASE-RXA Software

Download and install the GRL Platform Solutions software as follows:

1. If the GRL Platform Solutions software is to be installed on a PC (where it is referred to as 'controller PC'), install VISA (Virtual Instrument Software Architecture) on to the PC where GRL-PXE6-BASE-RXA is to be used (see Section 2.2).
2. Download the software ZIP file package from the GRL Platform Solutions support site.
3. The ZIP file contains:
  - a) **PCle6\_0\_BaseANPatternFilesInstallationxxxxxxxxxxSetup.exe** – Run this on the Anritsu MP1900A BERT Signal Quality Analyzer to install the pattern setup files.
  - b) **PCIEGen6ANBaseSpecTestApplicationxxxxxxxxxxSetup.exe** – Run this on the controller PC or oscilloscope to install the GRL-PXE6-BASE-RXA application.
  - c) **PCle6\_0\_BaseANRxTestScopeSetupFilesInstallationxxxxxxxxxxSetup.exe** – Run this on the oscilloscope to install the scope setup files.

#### 3.2 Launch and Set Up Software

1. Once the software is installed, open the GRL folder from the Windows Start menu. Click on **GRL – Automated Test Solutions** within the GRL folder to launch the GRL Platform Solutions software framework.

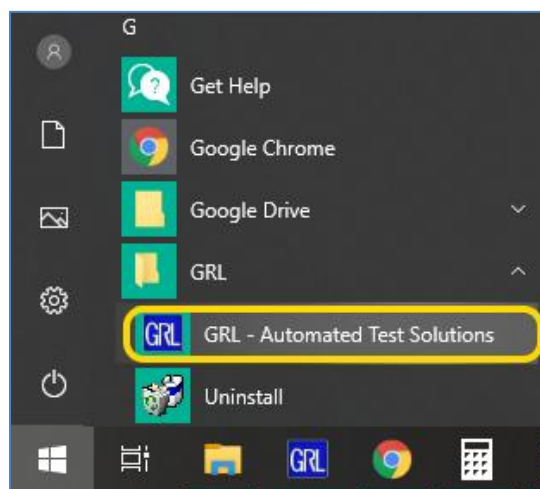


FIGURE 1. SELECT AND LAUNCH GRL PLATFORM SOLUTIONS FRAMEWORK

2. From the Application → Rx Test Solution drop-down menu, select “Anritsu PCIe 6.0 Base Rx Test” to start the PCIe 6.0 Base Rx Test Application. If the selection is grayed out, it means that your license has expired.

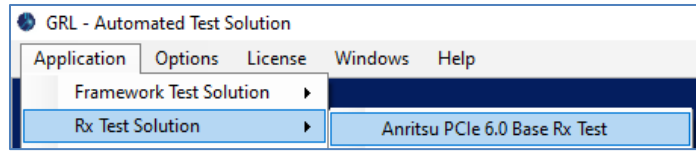


FIGURE 2. LAUNCH PCIe 6.0 BASE RX TEST APPLICATION

3. To enable license, go to License → License Info.

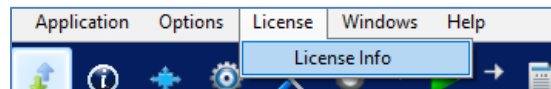


FIGURE 3. SEE LICENSE DETAILS

- a) Check the license status for the installed application.

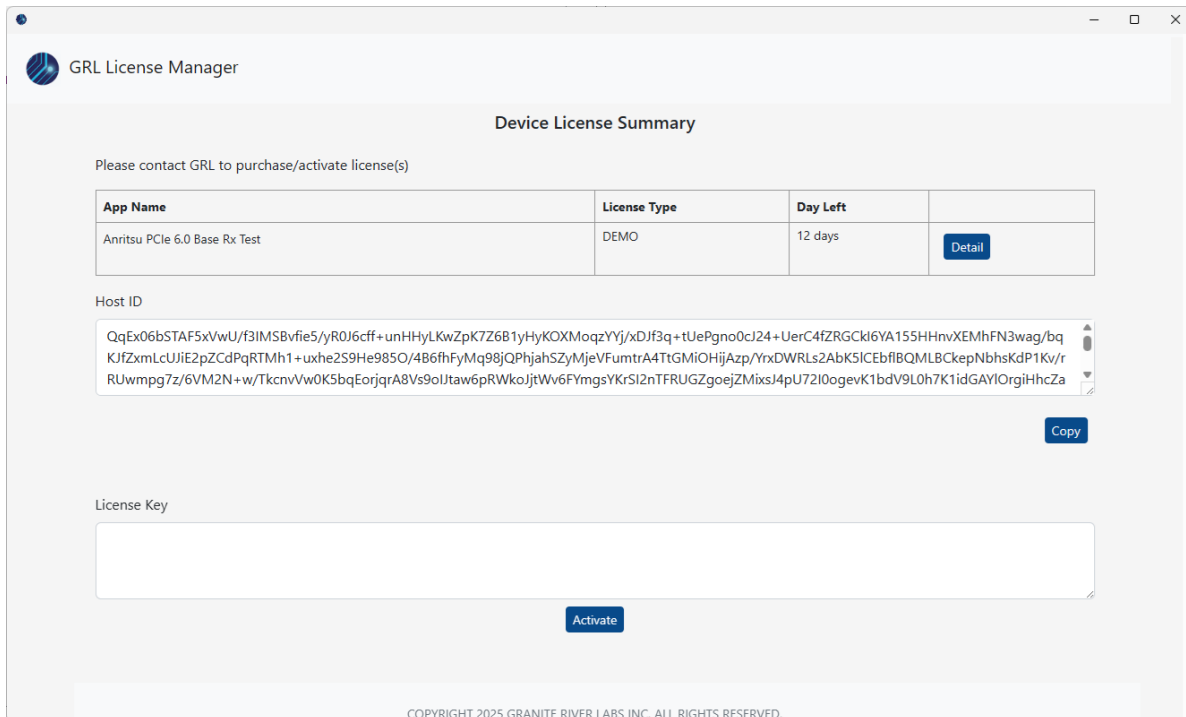


FIGURE 4. CHECK LICENSE FOR INSTALLED APPLICATIONS

- b) Activate a License:

- If you have an Activation Key, enter it in the **License Key** field provided and select **Activate**. The installed application is ready for use upon successful activation.
- If you do not have an Activation Key, close the above window to use a demo version of the application over a free 12-day trial period.

**Note:** Once the 12-day trial period ends, you will need to request an Activation Key to continue using the application on the same computer by contacting [support@grlps.com](mailto:support@grlps.com).

### 3.2.1 Connection Configuration

1. Connect the Anritsu MP1900A BERT via LAN to the GRL Platform Solutions automation control enabled Scope or PC. The BERT and MX183000A software can be connected using connection string formats similar to the following examples:

- BERT: “TCPIP0::192.168.0.14::5001::SOCKET” or “192.168.0.14:5001”
- MX183000A: “TCPIP0::192.168.0.14::5000::SOCKET” or “192.168.0.14:5000”

*Note the IP addresses listed above are only examples and should be changed according to the actual network connection being used.*

2. Connect the oscilloscope with the controller PC through either GPIB, USB or LAN.

*Note: Additional information for connecting the Keysight and Tektronix oscilloscopes to the controller PC is provided in the Appendix of this MOI.*

### 3.2.2 Launch and Set Up GRL-PXE6-BASE-RXA Software (on the Scope or Controller PC)

1. Launch the GRL Platform Solutions Host Application from “Start Menu → GRL → GRL – Automated Test Solutions”.
2. Select “Application → Rx Test Solution → Anritsu PCIe 6.0 Base Rx Test Application”.
3. On the Scope or controller PC, obtain the network addresses for all the connected instruments from the device settings. Note these addresses as they will be used to connect the instruments to the GRL-PXE6-BASE-RXA software.

4. On the Equipment Setup  page of the PCIe 6.0 Base Rx Test Application, type in the address of each connected instrument into the ‘Address’ field.

*(Note: If the GRL Platform Solutions software is installed on the **Tektronix Scope**, ensure the Scope is connected via GPIB and type in the GPIB network address, for example “GPIB8::1::INSTR”).*

If the GRL Platform Solutions software is installed on the PC to control the Scope, type in the Scope IP address, for example “TCPIP0::192.168.0.110::inst0::INSTR”. Note to **omit** the Port number from the address.

*(Note: If the GRL Platform Solutions software is installed on the **Keysight Scope**, and if there is error in connection, type in the Scope IP address as “TCPIP0::192.168.0.4::5025::SOCKET”).*

5. Then select the “lightning” button (  ) for each connected instrument.

The “lightning” button should turn green (  ) once the software has successfully established connection with each instrument.

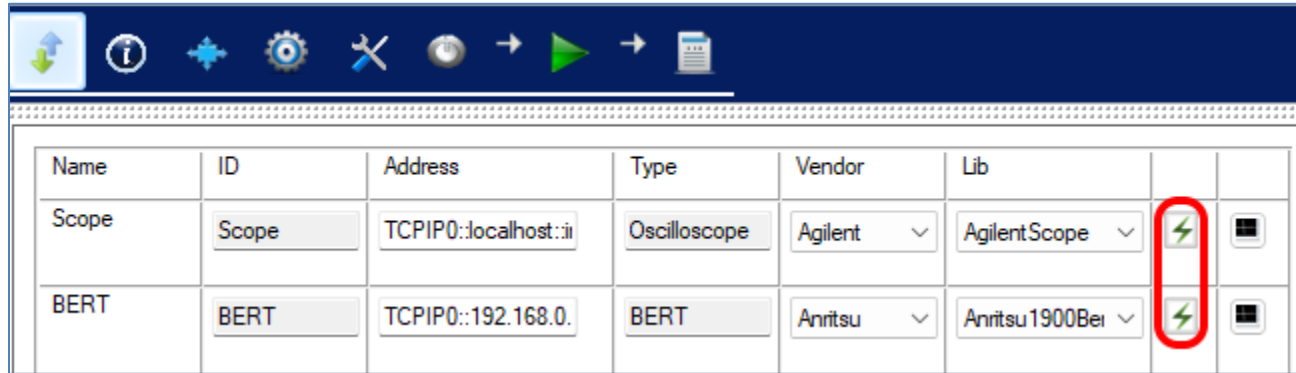


FIGURE 5. CONNECT INSTRUMENTS WITH GRL-PXE6-BASE-RXA SOFTWARE

### 3.3 Configuring the GRL-PXE6-BASE-RXA Software Before Calibration

Once all equipment is successfully connected from the previous section, proceed to set up the preliminary settings before going to the advanced measurement setup.

#### 3.3.1 Enter Test Session Information

Select  from the menu to access the **Session Info** page. Enter the information as required for the test session that is currently being run. The information provided will be included in the test report generated by the software once tests are completed.

- The fields under **DUT Info** and **Test Info** are defined by the user.
- The **Software Info** field is automatically populated by the software.

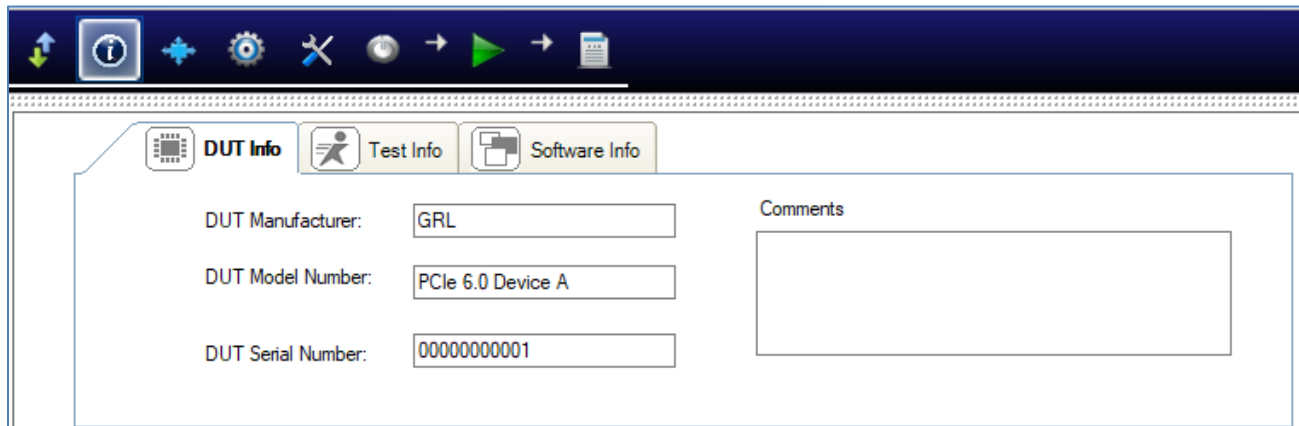


FIGURE 6. SESSION INFO PAGE

### 3.3.2 Set Measurement Conditions

Select  from the menu to access the **Conditions** page to set the conditions for calibration and testing.

Recommended procedure:

- **Step 1:** When calibrating, select all required conditions and perform the calibration.
- **Step 2:** Once calibration is completed and ready for testing, re-select the conditions that will be used for specific tests.

**SJ** tab: Select SJ Frequencies as defined by the Specification for calibration or testing.

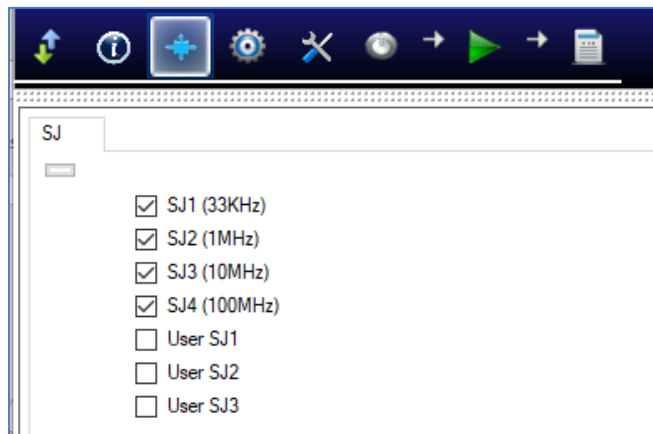


FIGURE 7. SELECT SJ FREQUENCIES

### 3.3.3 Set Up Measurement Requirements

Select  from the menu to access the **Setup Configuration** page. Use this page to configure the necessary measurement-related settings prior to running calibration and tests.

#### 3.3.3.1 User SJ Frequencies Setting

Set custom SJ frequencies to test for condition setup on the Conditions page.

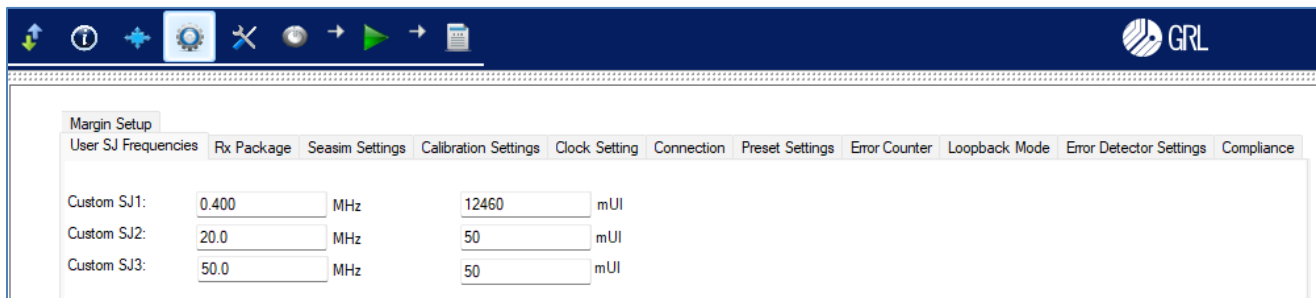


FIGURE 8. USER SJ FREQUENCIES SETTING

### 3.3.3.2 Rx Package Settings

Set up user-defined Rx Behavioral package to be applied during post processing analysis for the Eye Height and Eye Width Calibration.

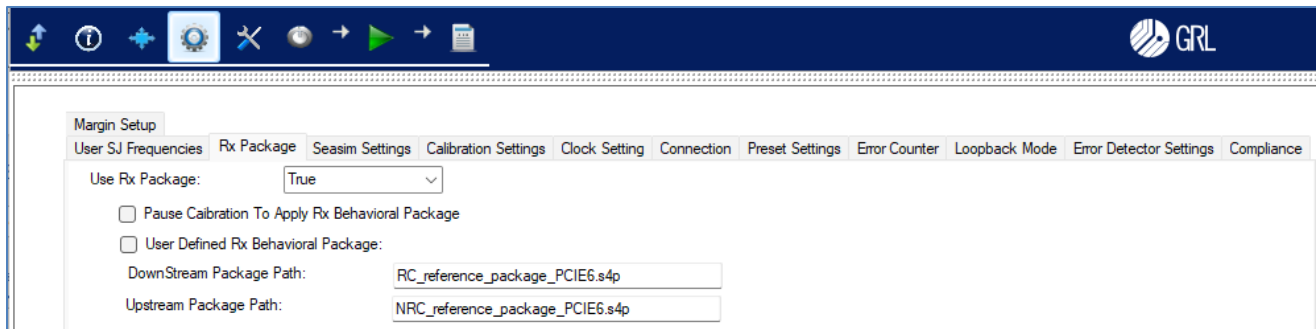


FIGURE 9. RX PACKAGE SETTINGS

### 3.3.3.3 Seasim Settings

Set the intrinsic noise and jitter (if required) to be used in the Seasim calculation.

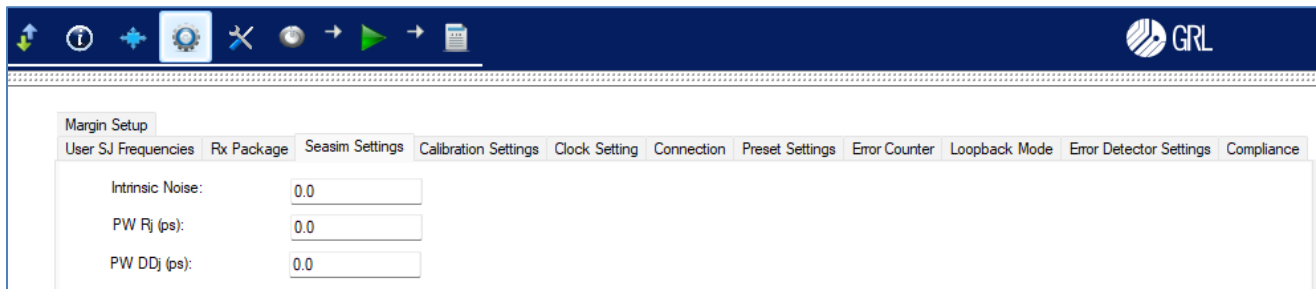


FIGURE 10. SEASIM SETTINGS

### 3.3.3.4 DM and CM Calibration Settings

Specify or use the default frequency values for Differential Mode (DM) and Common Mode (CM) calibration.



FIGURE 11. DM AND CM CALIBRATION SETTINGS

### 3.3.3.5 Clock Setup

Select the checkbox to enable Spread Spectrum Clock (SSC) capabilities for calibration and receiver testing (if supported by the DUT) for informative purpose. Set the Frequency and Deviation values for SSC.

Select the type of Rx Reference Clock architecture/mode to be used when testing the Rx DUT (depending on which clock mode is supported by the DUT). For the Common Clock

(CC) Refclk mode, a single Refclk source is applied for both the BERT signal generator and the DUT along with SSC and SJ mask. For the Independent Refclk (IR) mode, or in this case “Separate” Refclk mode, two Refclk sources are applied for both the BERT signal generator and the DUT along with independent SSC and SJ mask.

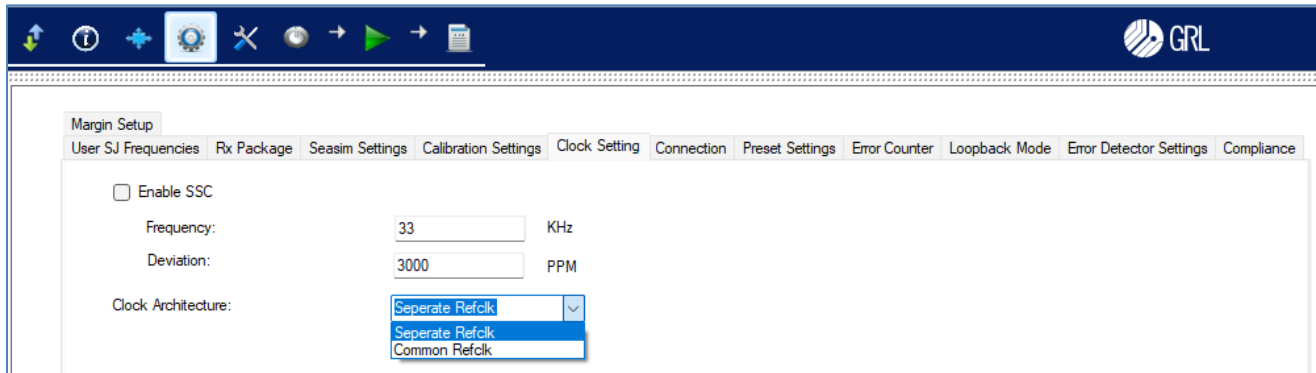


FIGURE 12. SSC AND REFCLK SETUP

### 3.3.3.6 Connection Setup

Set to use Real Edge connection for test setup on the Oscilloscope. *Note: This setting is only applicable for the Keysight Scope and will be disabled when the Tektronix Scope is used.*

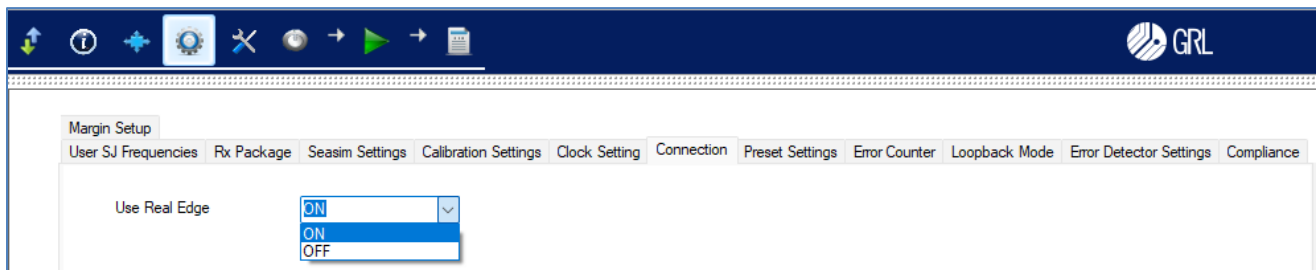


FIGURE 13. CONNECTION SETUP

### 3.3.3.7 Preset Settings

Select the preset to use, and optionally custom Pre-shoot and De-emphasis settings.

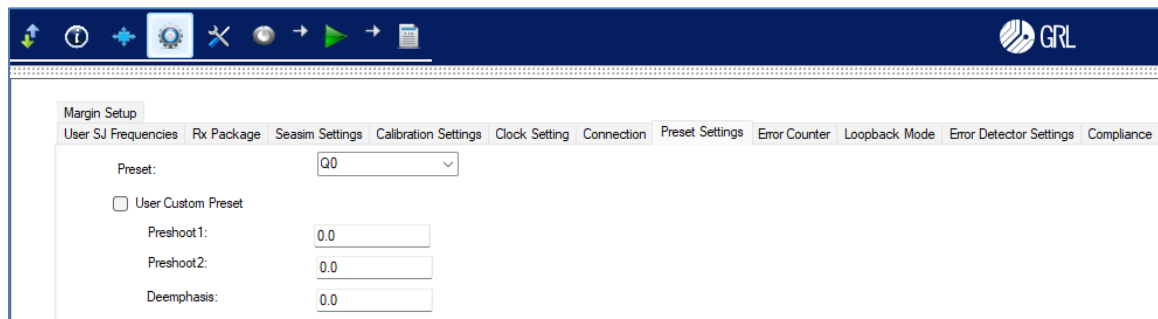


FIGURE 14. PRESET SETTINGS

### 3.3.3.8 Error Counter Setup

Enable loopback test mode for the Rx base DUT for error detection. If the DUT can be configured to loopback mode, select 'LoopBack', if not select 'Manual'.

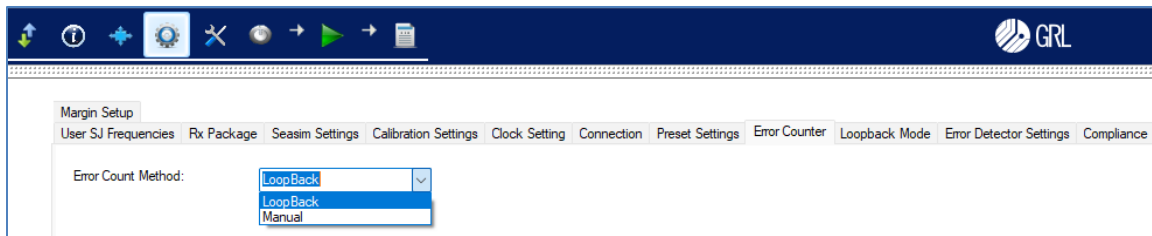


FIGURE 15. BER LOOPBACK TEST METHOD

### 3.3.3.9 Loopback Mode Setup

If "LoopBack" has been selected from the Error Counter tab, then select "Clock Recovery" in the Clock Recovery Method drop-down on the Loopback Mode tab. *Other options on the Clock Recovery Method drop-down are not yet supported.* Select to apply the default Jitter Tolerance loop bandwidth type or manually define the loop bandwidth values for the clock recovery.

If a Custom Pattern is to be used for error detection analysis, select the checkbox and then select the test pattern type and enable/disable coders. If the checkbox is not selected, a default test pattern will be used.

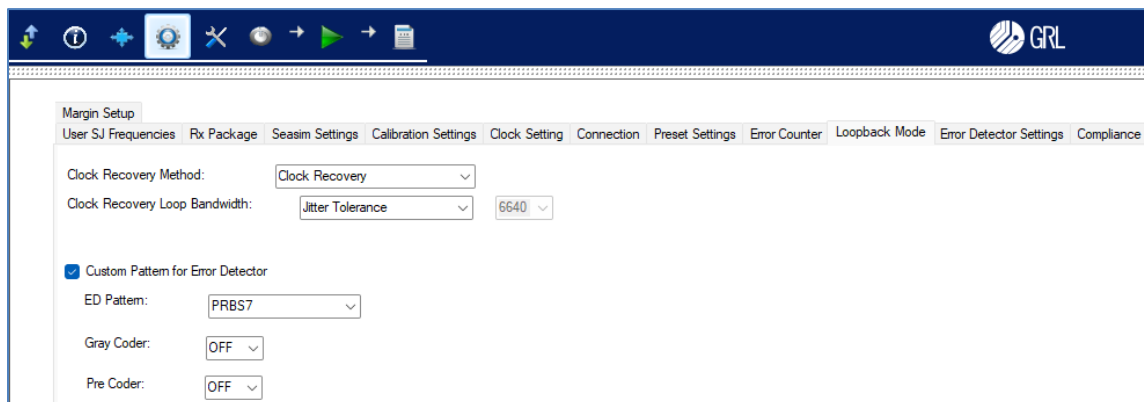


FIGURE 16. LOOPBACK MODE SETUP

### 3.3.3.10 Error Detector Setup

Enable or disable CTLE and Skip Ordered Set (SKP OS) symbol filtering for BER testing.

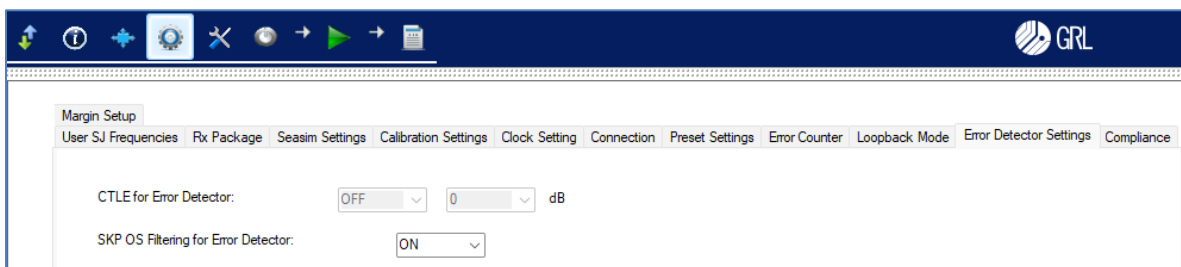


FIGURE 17. BER TEST SETUP

### 3.3.3.11 Compliance BER Setup

Set the allowable BER, Gating Time and Maximum Error limits to be tested for compliance. By default, these limits are set to Specification, but can be defined by the user. In normal circumstances, any error count above one constitutes a fail.

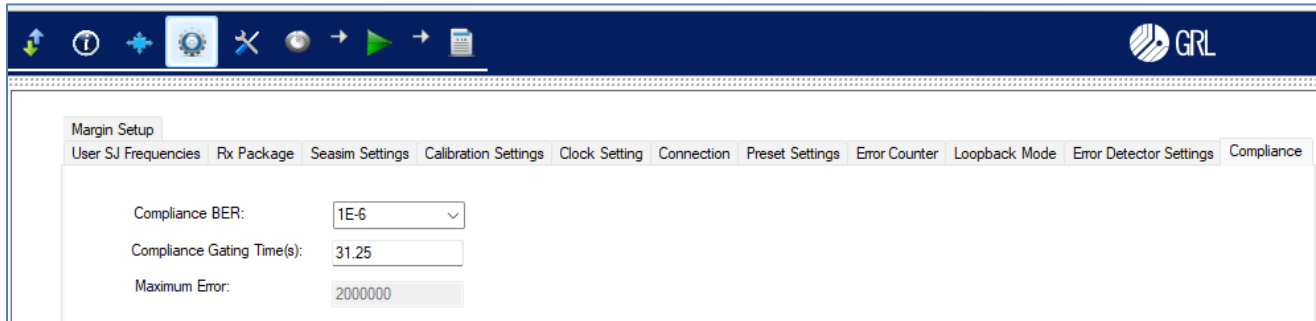


FIGURE 18. COMPLIANCE BER, GATING TIME AND MAXIMUM ERRORS SETUP

### 3.3.3.12 Margin Setup

Select the target BER, step size, gating time and limits to be applied during marginal testing.

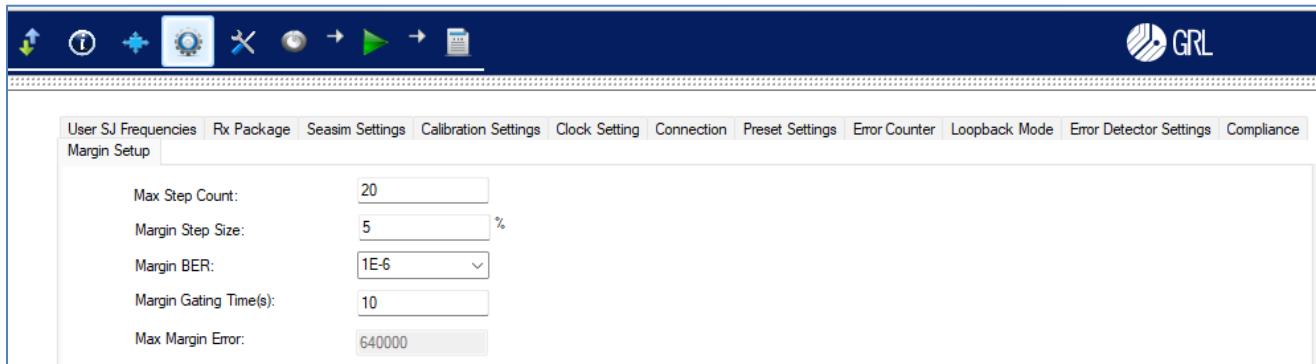


FIGURE 19. MARGIN SEARCH PARAMETERS SETUP

## 4 Calibrating Using GRL-PXE6-BASE-RXA Software

Calibration for PCI Express 6.0 Base Specification are performed at two physical test points – TP1 and TP2. TP1 is a physical test point for calibration without the effect of a channel. An adjustable calibration channel is defined that is to be used along with the replica channel for stressed eye calibration. After calibration the signal source will go through the breakout channel to the DUT for Rx compliance testing. TP2 is a physical test point that will affect the eye opening due to trace length. Post processing analysis of the signal is performed at the TP2P test point using the Seasim application to simulate the stressed eye opening after applying Rx Behavioral package, Rx CTLE, and DFE (if required).

To calibrate the stressed eye at TP2, the calibration channel shall receive signals with appropriate test patterns generated by the signal source. After calibration the signal source shall be used for testing Rx DUT compliance.

*Note: Calibration for the differential voltage swing and Tx equalization of the signal source are performed at the TP1 test point. Overall calibration channel loss shall be determined after the TP1 test point. Calibration channel is 32 dB nominally (informative) for 64.0 GT/s (including Rx package).*

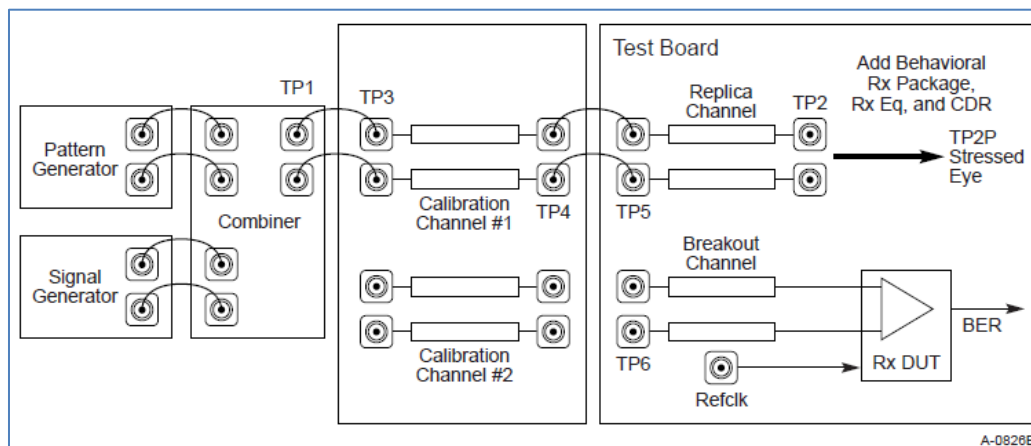


FIGURE 20. RX CALIBRATION/TEST SCHEMATIC OVERVIEW FROM THE PCIe 6.0 BASE SPECIFICATION

| Data Rate               | $F_{LOW-IL-MIN}$ | $F_{LOW-IL-MAX}$ | $F_{HIGH-IL-MIN}$ | $F_{HIGH-IL-MAX}$ |
|-------------------------|------------------|------------------|-------------------|-------------------|
| 64.0 GT/s Root Port     | 3.0 dB @ 1 GHz   | 4.0 dB @ 1 GHz   | 23.5 dB @ 16 GHz  | 24.5 dB @ 16 GHz  |
| 64.0 GT/s Non-Root Port | 3.6 dB @ 1 GHz   | 4.6 dB @ 1 GHz   | 27.5 dB @ 16 GHz  | 28.5 dB @ 16 GHz  |

FIGURE 21. CALIBRATION CHANNEL IL LIMITS FROM THE PCIe 6.0 BASE SPECIFICATION

The following return loss mask applies for either end of the 64.0 GT/s calibration channel:

- $\leq -12$  dB for  $< 4$  GHz
- $\leq -10$  dB for  $\geq 4$  GHz and  $< 16$  GHz
- $\leq -6$  dB for  $\geq 16$  GHz and  $\leq 32$  GHz

## 4.1 Calibration for TP1 (Output of BERT Generator)

### 4.1.1 Setup for TP1 Calibration

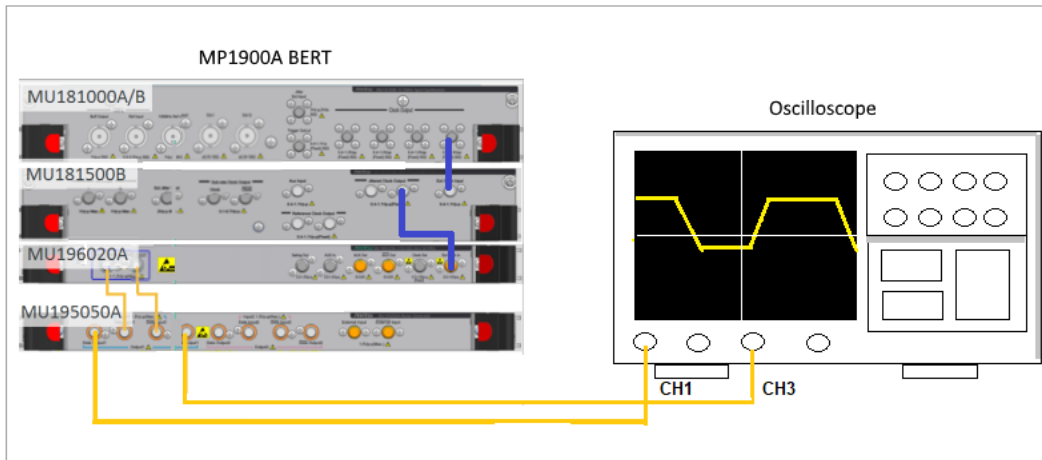


FIGURE 22. TYPICAL SETUP FOR TP1 CALIBRATION

#### Connection Steps:

1. Using a SMA-SMA short cable, connect the MU181000A/B clock output to the MU181500B Ext clock input.
2. Using a SMA-SMA short cable, connect the MU181500B jittered clock output to the MU196020A Ext clock input.
3. Using Anritsu J1792A coaxial cables, connect the MU196020A data outputs to the MU195050A data inputs.
4. Using phase matched K-K coaxial cables, connect the MU195050A data outputs to Channels 1 and 3 on the oscilloscope.

#### 4.1.1.1 TP1 Calibration Setup with Tektronix ATI Based Oscilloscope

If the Tektronix ATI based oscilloscope is being used, proceed with the following TP1 calibration setup.

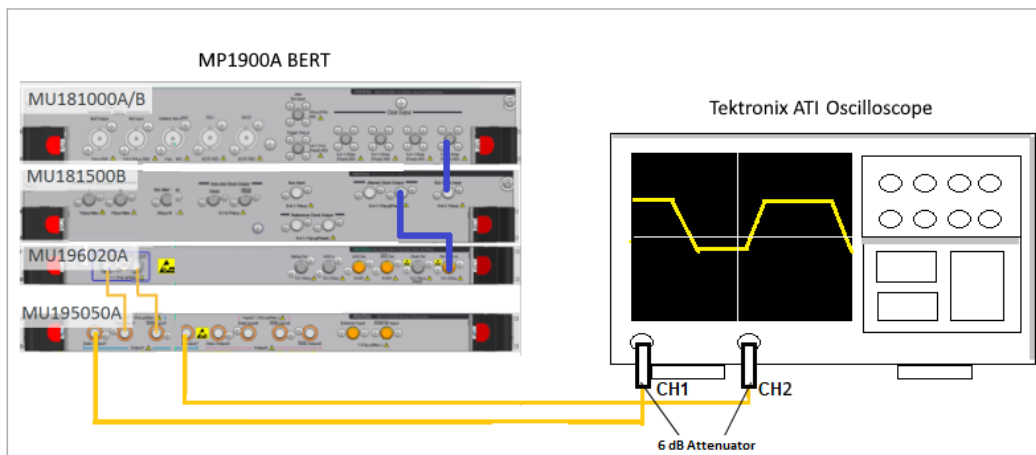


FIGURE 23. RECOMMENDED SETUP FOR TP1 CALIBRATION USING TEKTRONIX ATI SCOPE

*Note: Make sure that the “Tektronix Scope Configuration” is set to **Dual ATI** in the Configurations page (see Section 4.1.3).*

1. Follow back the same connections from step 1 to 4 in Section 4.1.1 above.
2. Then using phase matched K-K coaxial cables, connect the MU195050A data outputs to Channels 1 and 2 on the Tektronix ATI based oscilloscope through 6 dB attenuators.

#### 4.1.2 Select Calibration

The following calibration are defined at the TP1 and TP2 Test Points.

##### **Calibration at TP1:**

1. Channel Deskew
2. Initial Preset Q0 Calibration
3. Launch Amplitude Calibration
4. Preset Q0-Q9 Calibration
5. RJ Calibration
6. SJ Calibration
7. SJ Tone Calibration

##### **Calibration at TP2, can be Downstream (for Host) or Upstream (for Device):**

8. Downstream or Upstream:
  - a. Common Mode (CM) Sinusoidal Interference Calibration
  - b. Differential Mode (DM) Sinusoidal Interference Calibration (Achieves Calibrated Eye Height)
  - c. Optimized Preset
  - d. Stressed Jitter Voltage Calibration (Final stressed voltage and jitter eye adjustment to achieve Calibrated Eye Width using the Seasim calibration method)

The GRL-PXE6-BASE-RXA software automatically calibrates these parameters when initiated. See Appendix for an implementation method with automation for the above calibration.

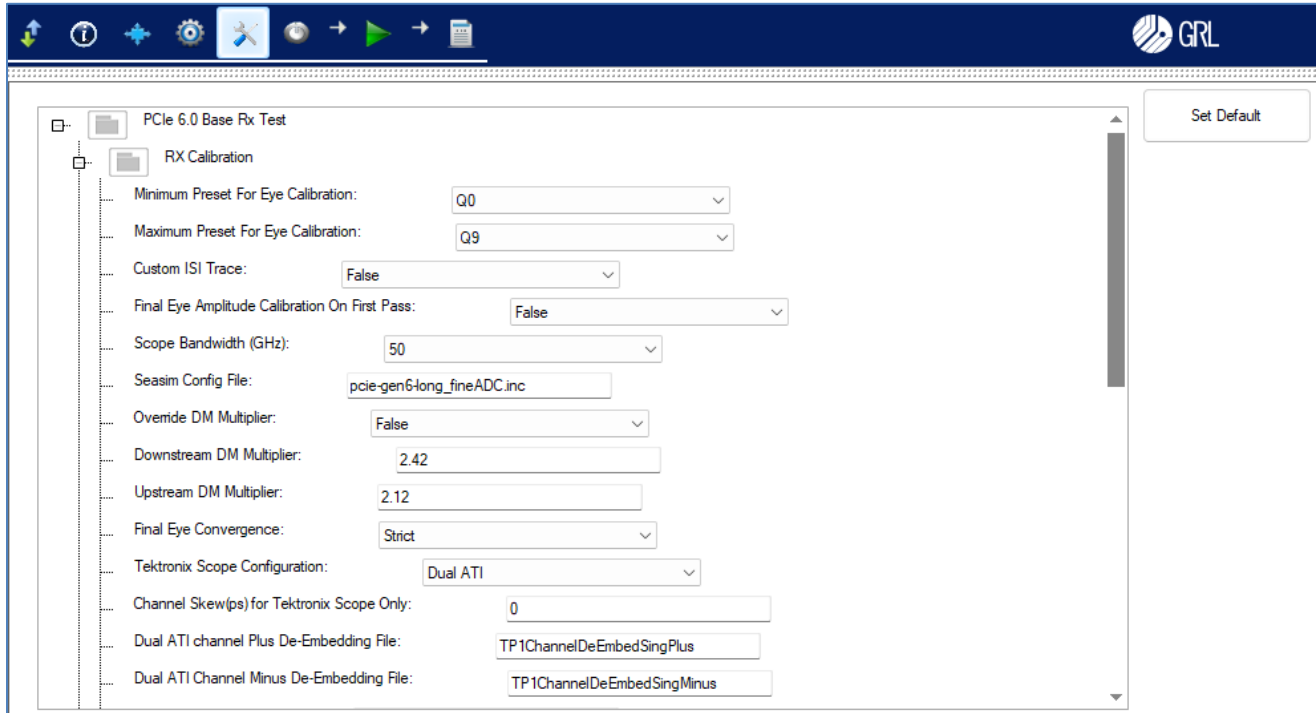
PCIe 6.0 Base Rx Test

- ☒
 RX Calibration
  - ☒
 TP1 Calibration
    - ☒
 Channel Deskew
    - ☒
 Initial Preset Q0 Calibration
    - ☒
 Launch Amplitude Calibration
    - ☒
 Preset Calibration
      - ☒
 Preset Q0 Calibration
      - ☒
 Preset Q1 Calibration
      - ☒
 Preset Q2 Calibration
      - ☒
 Preset Q3 Calibration
      - ☒
 Preset Q4 Calibration
      - ☒
 Preset Q5 Calibration
      - ☒
 Preset Q6 Calibration
      - ☒
 Preset Q7 Calibration
      - ☒
 Preset Q8 Calibration
      - ☒
 Preset Q9 Calibration
    - ☒
 Rj Calibration
    - ☒
 Sj Calibration
    - ☒
 SJ Tone Calibration
  - ☒
 Downstream
    - ☒
 Breakout + Long Channel
      - ☒
 CM Sinusoidal Interference Calibration (Long) (Downstream)
      - ☒
 DM Sinusoidal Interference Calibration (Long) (Downstream)
    - ☒
 Stress Cal
      - ☒
 Seasim Calibration (Downstream)
        - ☒
 Optimized Preset (Long) (Downstream)
        - ☒
 Stressed Jitter Voltage Calibration (Long) (Downstream)
  - ☒
 Upstream
    - ☒
 Breakout + Long Channel
      - ☒
 CM Sinusoidal Interference Calibration (Long) (Upstream)
      - ☒
 DM Sinusoidal Interference Calibration (Long) (Upstream)
    - ☒
 Stress Cal
      - ☒
 Seasim Calibration (Upstream)
        - ☒
 Optimized Preset (Long) (Upstream)
        - ☒
 Stress Jitter Voltage Calibration (Long) (Upstream)

Page 22 of 49

### 4.1.3 Configure Calibration Parameters

After selecting the desired calibration, the user can select  from the menu to access the **Configurations** page. Set the required parameters for calibration as described below. To return all parameters to their default values, select the 'Set Default' button.



The screenshot displays the 'RX Calibration' configuration page. The parameters and their current values are as follows:

- Minimum Preset For Eye Calibration: Q0
- Maximum Preset For Eye Calibration: Q9
- Custom ISI Trace: False
- Final Eye Amplitude Calibration On First Pass: False
- Scope Bandwidth (GHz): 50
- Seasim Config File: pcie-gen6-long\_fineADC.inc
- Override DM Multiplier: False
- Downstream DM Multiplier: 2.42
- Upstream DM Multiplier: 2.12
- Final Eye Convergence: Strict
- Tektronix Scope Configuration: Dual ATI
- Channel Skew(ps) for Tektronix Scope Only: 0
- Dual ATI channel Plus De-Embedding File: TP1ChannelDeEmbedSingPlus
- Dual ATI Channel Minus De-Embedding File: TP1ChannelDeEmbedSingMinus

FIGURE 25. CALIBRATION PARAMETERS CONFIGURATION PAGE

TABLE 4. CALIBRATION PARAMETERS DESCRIPTION

| Parameter                                               | Description                                                                                                              |
|---------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------|
| <b>Minimum &amp; Maximum Preset for Eye Calibration</b> | Select the range of presets to be applied for stressed eye calibration.                                                  |
| <b>Custom ISI Trace</b>                                 | Select 'True' to enable generating custom ISI trace for ISI calibration.                                                 |
| <b>Final Eye Amplitude Calibration On First Pass</b>    | Select 'True' to allow the final stressed voltage/jitter eye to be calibrated over the first attempt of calibration run. |
| <b>Scope Bandwidth (GHz)</b>                            | Select the bandwidth supported by the oscilloscope in use.                                                               |
| <b>Seasim Config File</b>                               | Enter the specific Seasim configuration template file to be used for Seasim measurements.                                |
| <b>Override DM Multiplier</b>                           | Select 'True' to use the upstream/downstream multiplier value for estimation of Differential Mode (DM) at TP2.           |
| <b>Downstream &amp; Upstream DM Multiplier</b>          | Enter the multiplier value for conversion of DM at TP2P to TP2 for downstream and upstream devices.                      |
| <b>Final Eye Convergence</b>                            | Select 'Strict' to ensure that final eye width and height from                                                           |

|                                                            |                                                                                                                                                                                      |
|------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|                                                            | eye calibration converge within specification beyond prediction curve.                                                                                                               |
| <b>Tektronix Scope Configuration</b>                       | If the Tektronix Scope is to be used for measurements, select either the Single-shot based Scope or the Tektronix' owned Dual Asynchronous Time Interleaving (Dual ATI) based Scope. |
| <b>Channel Skew (ps) for Tektronix Scope Only</b>          | If the Tektronix ATI based Scope is to be used for measurements, enter the channel skew or timing to perform alignment of the Scope channels.                                        |
| <b>Dual ATI Channel Plus &amp; Minus De-Embedding File</b> | If the Tektronix ATI based Scope is to be used for measurements, specify the file name for de-embedding on the respective Scope channel.                                             |
| <b>Scope Rj (ps RMS)</b>                                   | Set the random jitter (RJ) of the Scope in ps RMS.                                                                                                                                   |
| <b>Seasim Version</b>                                      | Select the version of Seasim to be used.                                                                                                                                             |
| <b>Amplitude Trigger Setting</b>                           | Select the Auto or Manual trigger mode to be set for the amplitude signal.                                                                                                           |
| <b>Amplitude Trigger Level (mV)</b>                        | Set the trigger level for the amplitude signal.                                                                                                                                      |
| <b>Preset Q0 HF Amplitude Compensation (%)</b>             | Set the Preset Q0 high frequency amplitude loss compensation in percentage.                                                                                                          |
| <b>Q0-Q10 Preset Calibration Max Iteration</b>             | Select the maximum number of runs or iterations to perform the Preset Q0 to Q10 calibration.                                                                                         |
| <b>Q0-Q10 Preset Calibration Limit</b>                     | Select the threshold limit value for the Preset Q0 to Q10 calibration.                                                                                                               |
| <b>Opposite Emphasis Measurement by Median</b>             | Select 'True' to enable the median to be used as reference for the inverse emphasis measurement.                                                                                     |
| <b>Feedback Gain Order</b>                                 | Select the CTLE gain value adjustment in controlled steps or variable mode to determine the lowest CTLE gain value that gives zero errors.                                           |
| <b>Preset Non Transition Region</b>                        | Select the preset equalization setting during the stable operational 64 GT/s state of the link.                                                                                      |
| <b>Launch Amplitude Cal Min Limit</b>                      | Set the minimum limit value for the launch amplitude calibration.                                                                                                                    |
| <b>Use Amplitude Feedback</b>                              | Select 'True' to enable amplitude feedback via the link equalization training where the receiver will provide feedback to the transmitter for signal quality optimization.           |
| <b>Amplitude Feedback Limit (%)</b>                        | If 'Use Amplitude Feedback' is set to 'True', select the allowable limit for the amplitude feedback.                                                                                 |
| <b>Negative DeEmphasis Method</b>                          | Select the method to emulate the effects of channel losses via negative de-emphasis to create high-frequency losses in the generated signal.                                         |

|                  |                                         |
|------------------|-----------------------------------------|
| <b>nUI Count</b> | Enter the number of nUI to be captured. |
|------------------|-----------------------------------------|

#### 4.1.4 Run Calibration at TP1

Select  from the menu to select the following run options and then start running the selected calibration.

- **Skip Test if Result Exists**– If previous calibration results exist, the GRL Platform Solutions software will *skip* the calibration steps that have existing reports.
- **Replace if Result Exists**– If previous calibration results exist, the GRL Platform Solutions software will *replace* each step in the calibration with new results.

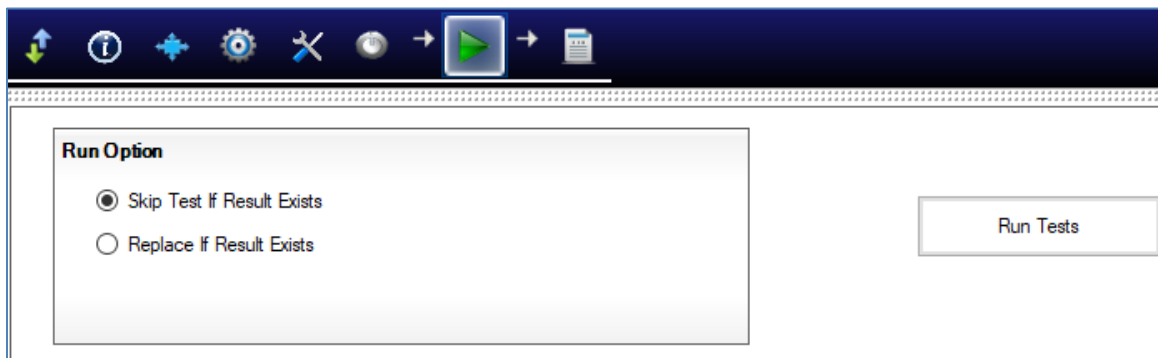


FIGURE 26. RUN TESTS

Select the **Run Tests** button to start running calibration.

When running calibration at TP1, the GRL Platform Solutions software will display the connection diagram as a first step to help the user make sure all connections are proper before calibration is performed. Example as below:

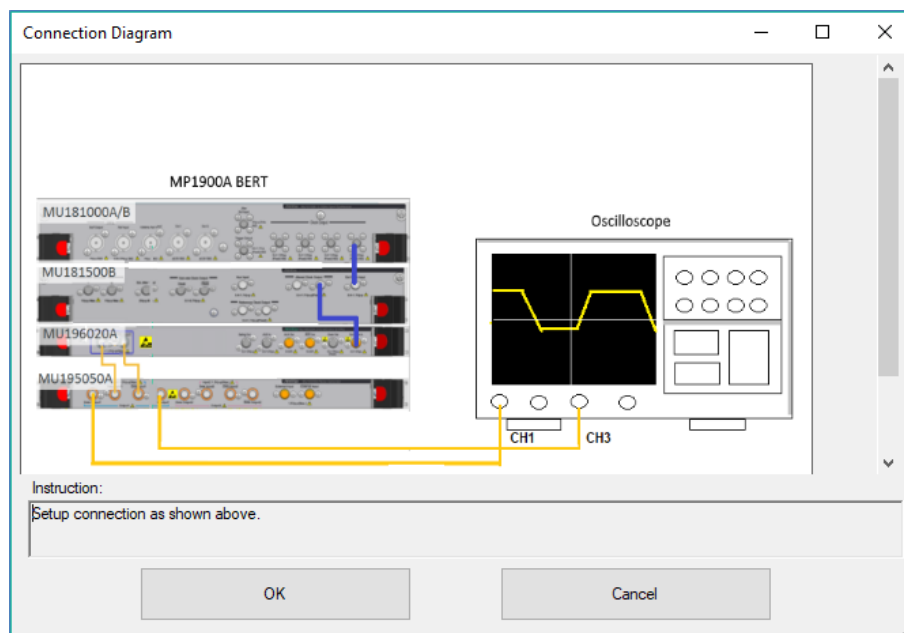


FIGURE 27. TP1 CONNECTION DIAGRAM DIALOG EXAMPLE

## 4.2 Calibration for TP2 (Output of Long Channel)

### 4.2.1 Setup for TP2 Calibration

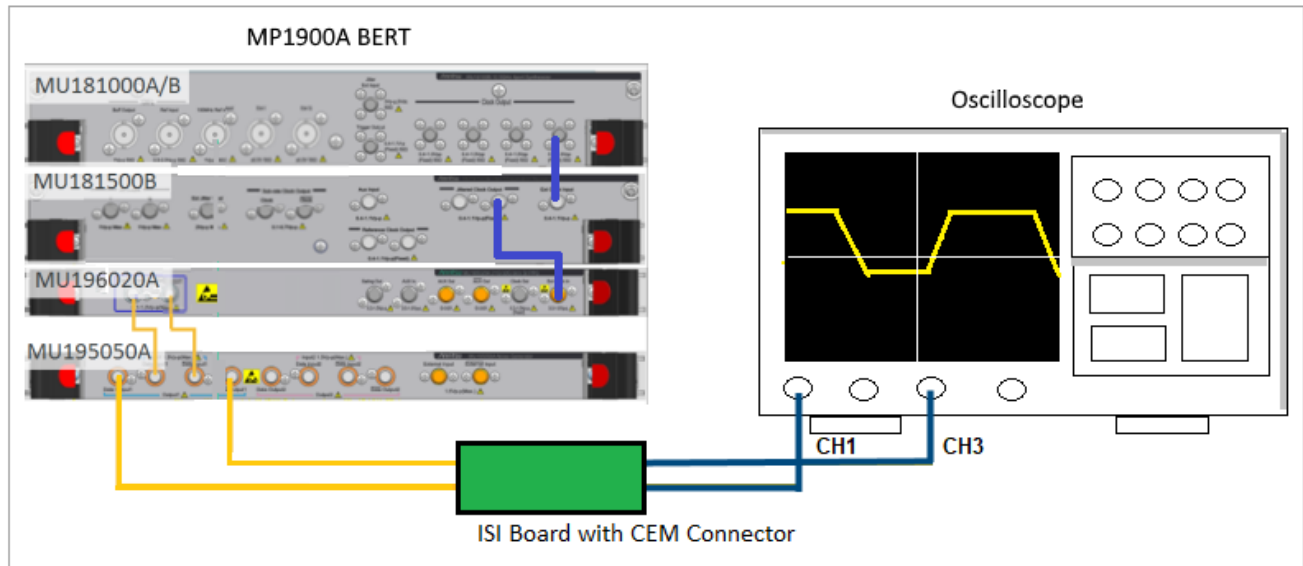


FIGURE 28. TYPICAL SETUP FOR TP2 CALIBRATION

#### Connection Steps:

1. Using back the same BERT connections from the TP1 calibration, disconnect the MU195050A data outputs from the oscilloscope channels.
2. Connect the MU195050A data outputs to an ISI board with CEM connector.
3. Connect the ISI board to Channels 1 and 3 on the oscilloscope.

#### 4.2.1.1 TP2 Calibration Setup with Tektronix ATI Based Oscilloscope

If the Tektronix ATI based oscilloscope is being used, proceed with the following TP2 calibration setup.

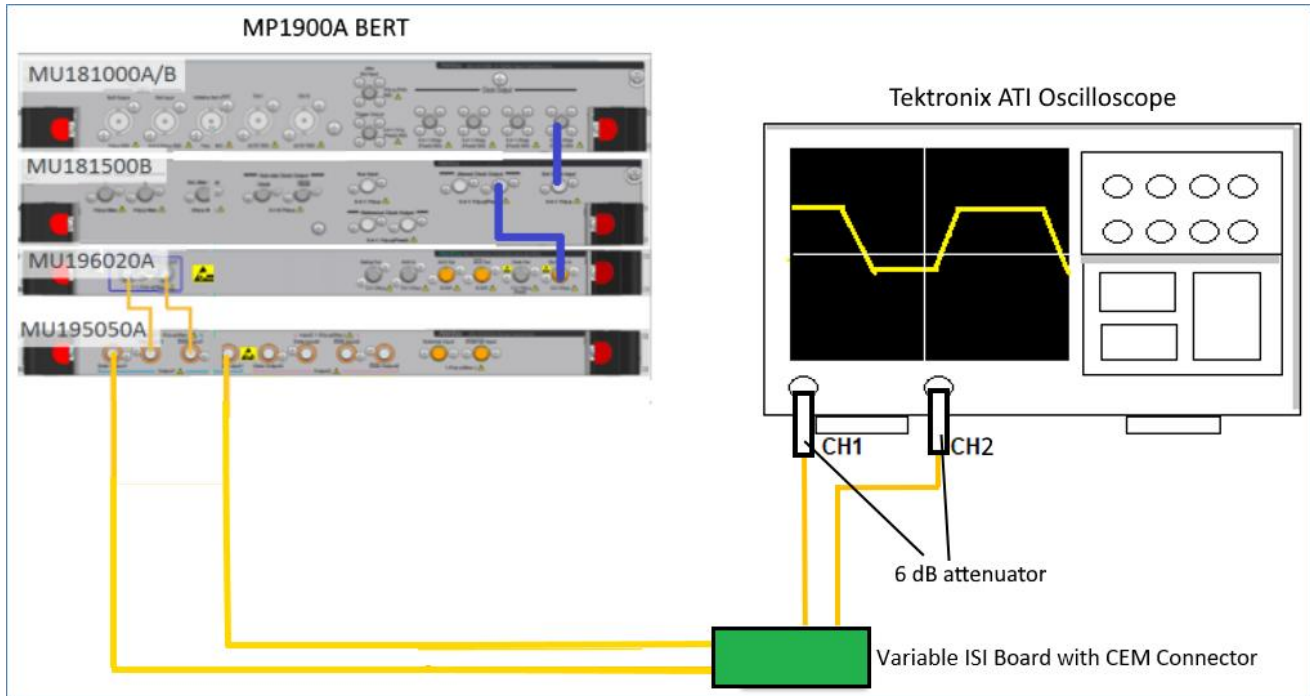


FIGURE 29. RECOMMENDED SETUP FOR TP2 CALIBRATION USING TEKTRONIX ATI SCOPE

*Note: Make sure that the “Tektronix Scope Configuration” is set to **Dual ATI** in the Configurations page (see Section 4.1.3).*

1. Using back the same BERT connections from the TP1 calibration in Section 4.1.1.1, disconnect the MU195050A data outputs from the oscilloscope channels.
2. Connect the MU195050A data outputs to a variable ISI board with CEM connector.
3. Then connect the variable ISI board to Channels 1 and 2 on the Tektronix ATI based oscilloscope through 6 dB attenuators.

### 4.2.2 Run Calibration Steps at TP2

Repeat Section 4.1.2 to complete the selected calibration steps at TP2.

After calibrating the loss profile to be used by adjustment of CM Sinusoidal Interference, DM Sinusoidal Interference and SJ to achieve calibrated eye height and width, the final calibrated stressed Eye diagram is calculated by Seasim and should look similar to the following example.

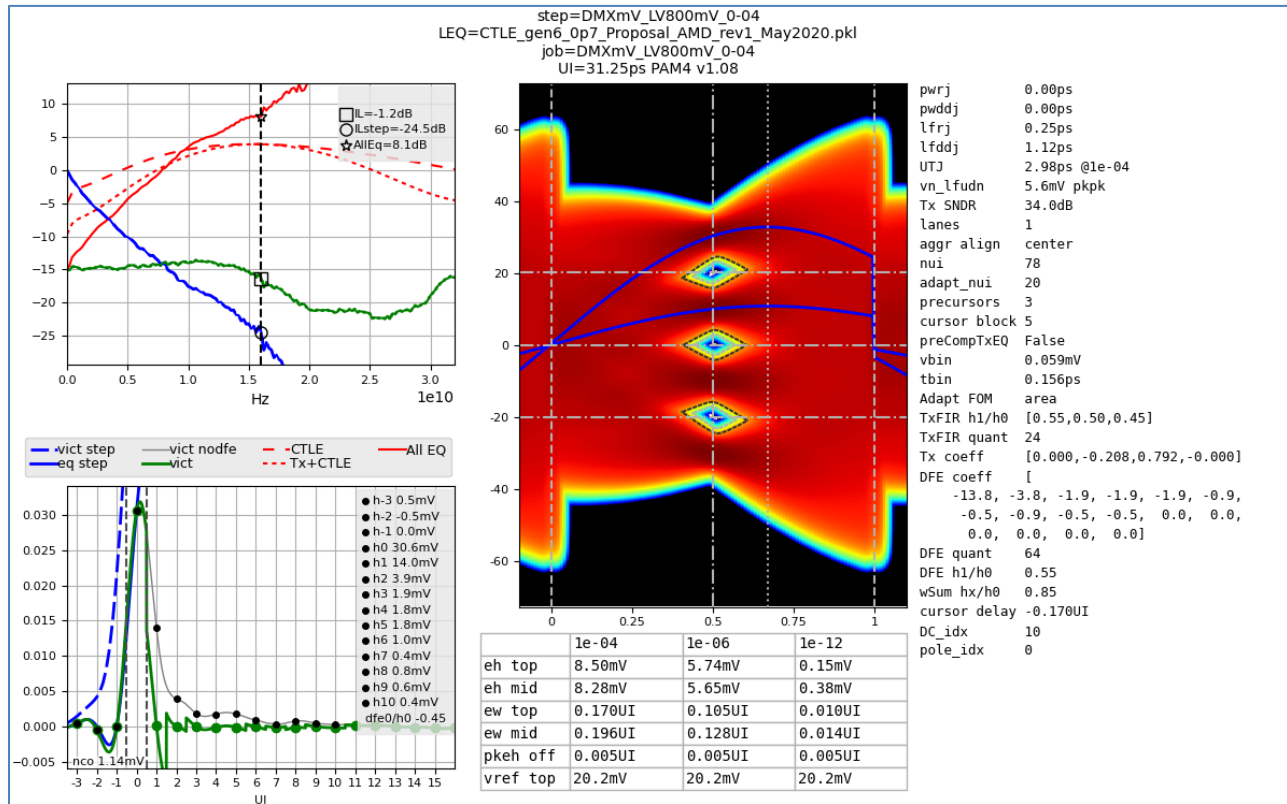


FIGURE 30. FINAL CALIBRATED STRESSED EYE DIAGRAM EXAMPLE

### 4.3 Configure Calibration Target Values

For debugging purposes ONLY, the default calibration target values can be changed for

the RJ and CM calibration. To do this, select  from the menu to access the Calibration page.

By default, the calibration target values are those defined in the specification. To change the values, un-select the Use Default Value checkbox. In case the default values are required again, just select the checkbox to allow all existing values to be reset to default.

*Note: The PID Control setting is used to adjust the step width for steps calculation if the target measurement cannot be met with the current step. To adjust, use a lower PID Control value to reduce the subsequent step or increase the control value to make the subsequent step bigger.*

↕ ℹ ⚙ ✂ 🔍 → ▶ → 📄

☒ Use Default Value

Launch Amplitude Calibration Rj Calibration CM Sinusoidal Interference Calibration (Long) (Downstream) CM Sinusoidal Interference Calibration (Long) (Upstream)

|               |                                     |   |
|---------------|-------------------------------------|---|
| Initial Cal   | <input type="text" value="500"/>    |   |
| Target Value: | <input type="text" value="0.85"/>   | V |
| Min Limit:    | <input type="text" value="0.8075"/> | V |
| Max Limit:    | <input type="text" value="0.8925"/> | V |
| PID Control   | <input type="text" value="700"/>    |   |

FIGURE 31. CALIBRATION TARGET OVERWRITE PAGE

## 5 Testing Using GRL-PXE6-BASE-RXA Software

Once the final stressed eye has been calibrated successfully, receiver stress jitter voltage tolerance and margin testing can then be performed on the device under test (DUT). The DUT should have a Replica Channel of the same Insertion Loss as the Replica Channel used for calibration. The Replica Channel is removed when performing the DUT tests.

The GRL-PXE6-BASE-RXA software automates the receiver compliance and jitter tolerance testing, at the spec-defined or user-defined jitter frequency steps. The GRL Platform Solutions software also supports nested loop testing of multiple parameters to facilitate silicon PVT testing or testing across multiple test conditions. When testing is completed, the results will be logged in an aggregated test report which can be generated into a PDF format.

Receiver device compliance ensures the receiver DUT is able to correctly interpret data from a received signal with valid voltage and timing characteristics by achieving an acceptable bit error rate (BER) of less than  $1E-6$ . The signal used for verifying receiver tolerance must contain the maximum allowable jitter, noise and signal loss. The stressed receiver tolerance test should include various differential mode sinusoidal interference, minimum transmitter voltage amplitude and jitter which includes random jitter and a sinusoidal periodic jitter component that is swept across specific frequency intervals.

Once the stressed receiver tolerance test setup has been calibrated, the BERT will transmit a modified compliance pattern to the receiver and monitors the loopback pattern has a BER that is less than  $1E-6$ .

### 5.1 Receiver DUT Compliance Test Setup

#### 5.1.1 Test Setup

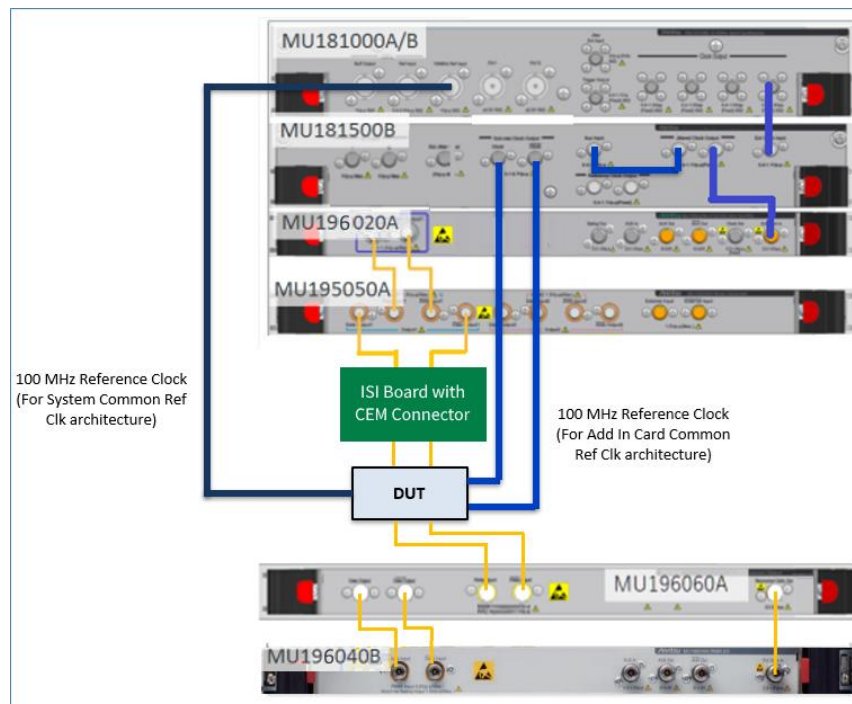


FIGURE 32. TYPICAL RECEIVER DUT TEST SETUP

### Connection Steps:

1. Using back the same BERT connections from calibration, remove the oscilloscope connections from the ISI channel.
2. Connect the jittered clock output to the Aux input on the MU181500B using a SMA-SMA short cable.
3. Using phase matched K-K coaxial cables, connect the ISI board with CEM connector to the DUT Rx inputs.
4. **If using an Add-in card DUT**, connect the MU181500B sub-rate clock outputs to the Ref Clk+/- of the DUT using coaxial cables.
5. **If using a System DUT**, connect the Ref Clk of the DUT to the 100 MHz Ref Input on the MU181000A/B with a BNC cable.
6. Using phase matched K-K coaxial cables, connect the DUT Tx outputs to the MU196060A Re-Driver data inputs.
7. Connect the MU196060A Re-Driver data outputs to the MU196040B data inputs for loopback error detection.
8. Connect the MU196060A Re-Driver clock output to the MU196040B Ext Clock in.

#### 5.1.1.1 Independent Refclk Mode (for System DUT SRIS Refclk Architecture)

The following receiver compliance test setup for the System DUT is similar to the above but uses an external Refclk source for testing in the IR Refclk mode.

Using back the same setup from Figure 32, remove the connection of the DUT's Ref Clk to the 100 MHz Ref Input on the MU181000A/B. The BERT will use its own internal Refclk which mimics an external Refclk source in this mode.

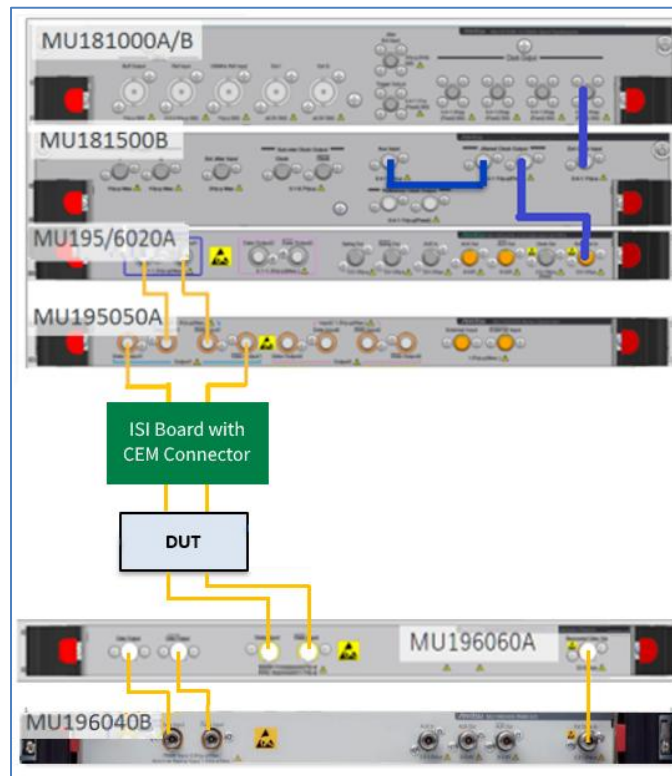


FIGURE 33. TYPICAL RECEIVER TEST SETUP FOR SYSTEM DUT SRIS REFCLK ARCHITECTURE

### 5.1.1.2 Independent Refclk Mode (for Add-In Card DUT SRIS Refclk Architecture)

The following receiver compliance test setup for the Add-in card DUT is similar to the above but uses an external Refclk source for testing in the IR Refclk mode.

Using back the same setup from Figure 32, remove the connections of the MU181500B sub-rate clock outputs to the Ref Clk+/- of the DUT. The user can choose to connect an external Refclk source to the Ref Clk+/- of the DUT or use the Board Refclk source from the DUT.

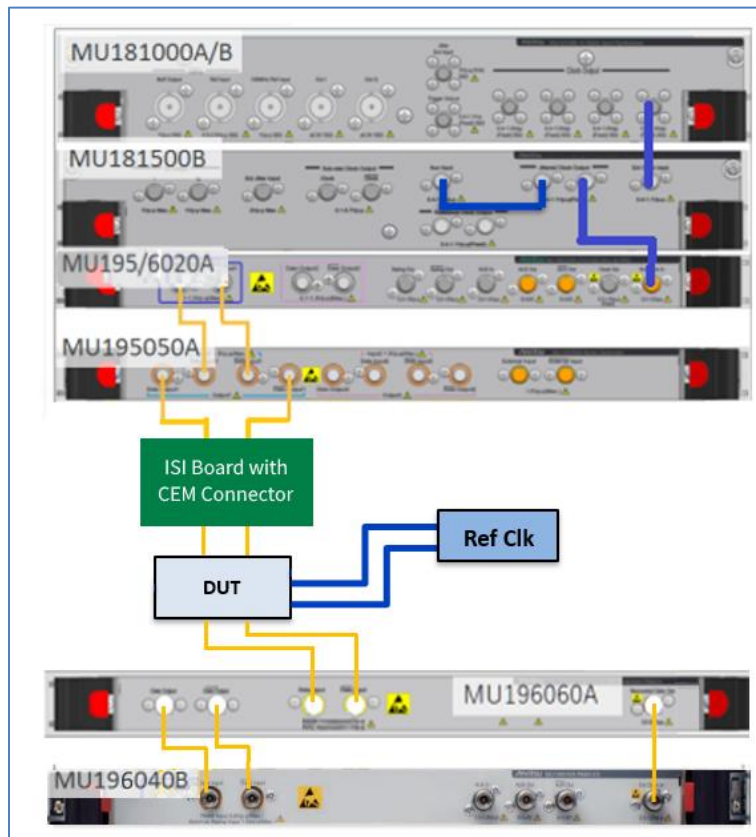


FIGURE 34. TYPICAL RECEIVER TEST SETUP FOR ADD-IN CARD DUT SRIS REFCLK ARCHITECTURE

### 5.1.2 Receiver Compliance Tests

In the following diagram, **Stress Jitter Voltage** tests are selected if tests at the Compliance Jitter Limits are to be performed.

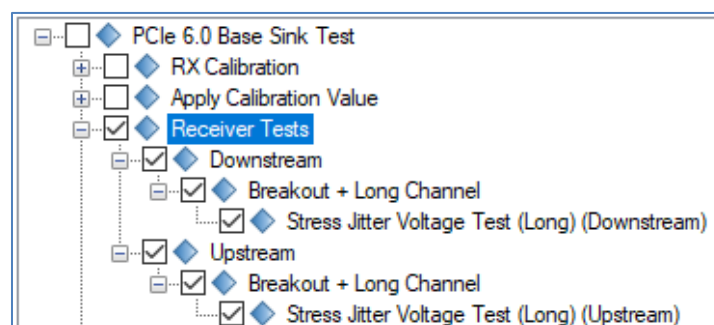


FIGURE 35. SELECTING RECEIVER COMPLIANCE TESTS

The stress jitter voltage tests are run from the same screen as shown in Figure 26.

### 5.1.3 Receiver Margin Tests

In the following diagram, **Stress Jitter Voltage Margin** tests are selected if Jitter Margin testing is to be performed.

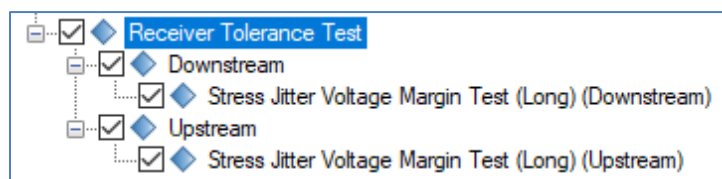


FIGURE 36. SELECTING RECEIVER MARGIN TESTS

The marginal tests are run from the same screen as shown in Figure 26.

### 5.1.4 Configure Receiver Test Parameters

Select  from the menu to access the **Configurations** page. Set the required parameters for testing as described below.

To return all parameters to their default values, select the 'Set Default' button.

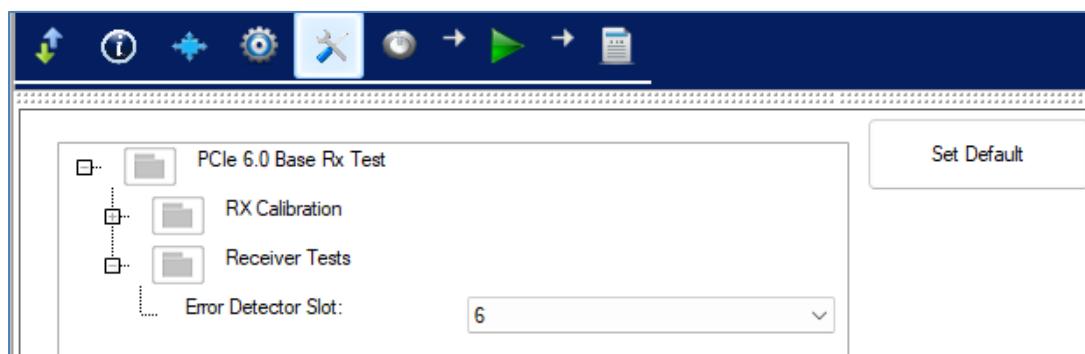


FIGURE 37. RECEIVER TEST PARAMETERS CONFIGURATION PAGE

TABLE 5. RECEIVER TEST PARAMETERS DESCRIPTION

| Parameter                  | Description                                                      |
|----------------------------|------------------------------------------------------------------|
| <b>Error Detector Slot</b> | Select to assign a different Slot number for the Error Detector. |

### 5.1.5 Apply Calibrated Values for Testing

Calibrated values from the stressed jitter voltage calibration can be used in the DUT Rx tests. To apply these values, select **Apply Stress Voltage Param**.

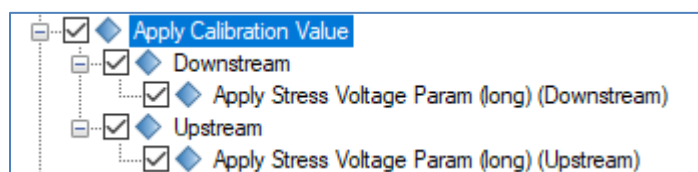


FIGURE 38. SELECTING TO APPLY CALIBRATION VALUES

## 5.2 Enable Loopback BER Test

To set up the GRL Platform Solutions software to automate loopback testing for error detection, go to the Configurations  menu and set up the following settings. *Make sure that the Rx DUT is capable of supporting loopback mechanism for BER measurements.*

1. Under the Error Counter tab, select 'LoopBack' to enable loopback test mode for the DUT (refer Section 3.3.3.8).
2. Under the Loopback Mode tab, select 'Clock Recovery' in the Clock Recovery Method field to apply the clock data recovery function to process the modified compliance pattern generated by the DUT (refer Section 3.3.3.9). Then, set the value for the Clock Recovery Loop Bandwidth by selecting 'Manual' or simply use the default 'Jitter Tolerance' values.

If using a user-defined pattern instead of the default test pattern for error checking, select the 'Custom Pattern for Error Detector' checkbox. Then, select the type of custom test pattern to be used.

3. Under the Error Detector Settings tab, choose to enable or disable CTLE and SKP OS symbol filtering as required in BER testing (refer Section 3.3.3.10).
4. If needed to change the default spec-defined limits for the target BER and maximum error allowed for BER measurements, then select the Compliance tab and define new values (refer Section 3.3.3.11).

## 6 Interpreting Test Report

The **Report** page has all the results from all the test runs displayed. If some of the results are not desired, they can be individually deleted by using the **Delete** button. Also for a PDF report, select the **Generate report** button. To have the calibration data plotted in the report, make sure the **Plot Calibration Data** box is checked.

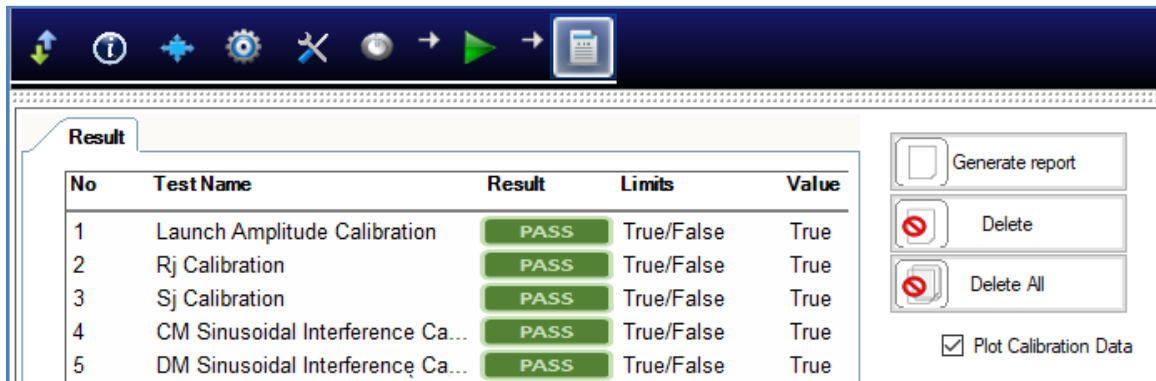


FIGURE 39. REPORT RESULTS PAGE

### 6.1 DUT Information

This portion is populated from the information in the DUT tab from the **Session Info** tab.

| Anritsu PCIe 6.0 Base Rx Test Report |                      |
|--------------------------------------|----------------------|
| <b>DUT Information</b>               |                      |
| DUT Manufacturer                     | : GRL                |
| DUT Model Number                     | : PCIe 6.0 Device A  |
| DUT Serial Number                    | : 000000000001       |
| DUT Comments                         | :                    |
| <b>Test Information</b>              |                      |
| Test Lab                             | : Granite River Labs |
| Test Operator                        | : David              |
| Test Date                            | : 20 June 2022       |
| <b>Software Version</b>              |                      |
| Software Revision                    | : 0.00.21            |

FIGURE 40. DUT INFORMATION

## 6.2 Summary Table

This portion is populated from the tests performed and its results. This gives an overall view of all the results and its test conditions.

| No | TestName                                                                   | Limits | Value | Results | SJ     |
|----|----------------------------------------------------------------------------|--------|-------|---------|--------|
| 1  | <a href="#">Pre-shoot1 Calibration</a>                                     | N/A    | N/A   | Pass    |        |
| 2  | <a href="#">Pre-shoot2 Calibration</a>                                     | N/A    | N/A   | Pass    |        |
| 3  | <a href="#">De-emphasis Calibration</a>                                    | N/A    | N/A   | Pass    |        |
| 4  | <a href="#">Launch Amplitude Calibration</a>                               | N/A    | N/A   | Pass    |        |
| 5  | <a href="#">Rj Calibration</a>                                             | N/A    | N/A   | Pass    |        |
| 6  | <a href="#">Sj Calibration</a>                                             | N/A    | N/A   | Pass    | SJLF_1 |
| 7  | <a href="#">Sj Calibration</a>                                             | N/A    | N/A   | Pass    | SJLF_2 |
| 8  | <a href="#">Sj Calibration</a>                                             | N/A    | N/A   | Pass    | SJLF_3 |
| 9  | <a href="#">Sj Calibration</a>                                             | N/A    | N/A   | Pass    | SJLF_4 |
| 10 | <a href="#">SJ Tone Calibration</a>                                        | N/A    | N/A   | Pass    |        |
| 11 | <a href="#">CM Sinusoidal Interference Calibration (Long) (Downstream)</a> | N/A    | N/A   | Pass    |        |
| 12 | <a href="#">DM Sinusoidal Interference Calibration (Long) (Downstream)</a> | N/A    | N/A   | Pass    |        |
| 13 | <a href="#">Optimized Preset (Long) (Downstream)</a>                       | N/A    | N/A   | Pass    |        |
| 14 | <a href="#">CM Sinusoidal Interference Calibration (Long) (Upstream)</a>   | N/A    | N/A   | Pass    |        |
| 15 | <a href="#">DM Sinusoidal Interference Calibration (Long) (Upstream)</a>   | N/A    | N/A   | Pass    |        |
| 16 | <a href="#">Optimized Preset (Long) (Upstream)</a>                         | N/A    | N/A   | Pass    |        |
| 17 | <a href="#">Stress Jitter Voltage Calibration (Long) (Upstream)</a>        | N/A    | N/A   | Pass    |        |

FIGURE 41. SUMMARY TABLE

## 6.3 Calibration/Test Results

If the Plot Calibration Data checkbox is checked, then the plots are shown in this part of the report.

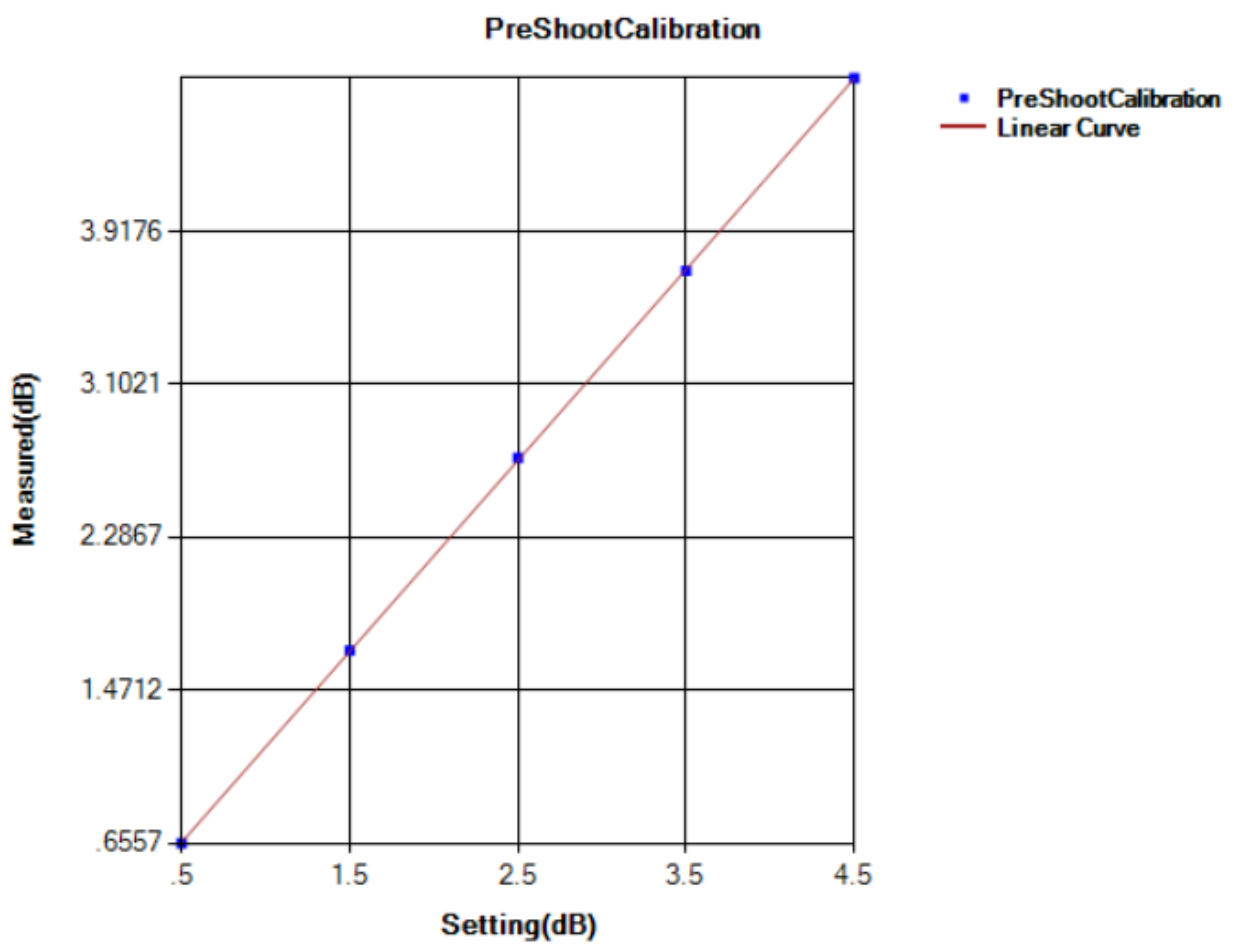
### 1. Pre-shoot1 Calibration

Pass/Fail Stats : Pass

Cal Parameter : PreShoot

Test completed time : 15 February 2022 2:12:41 AM

#### PreShootCalibration Plot



## Eye Opening

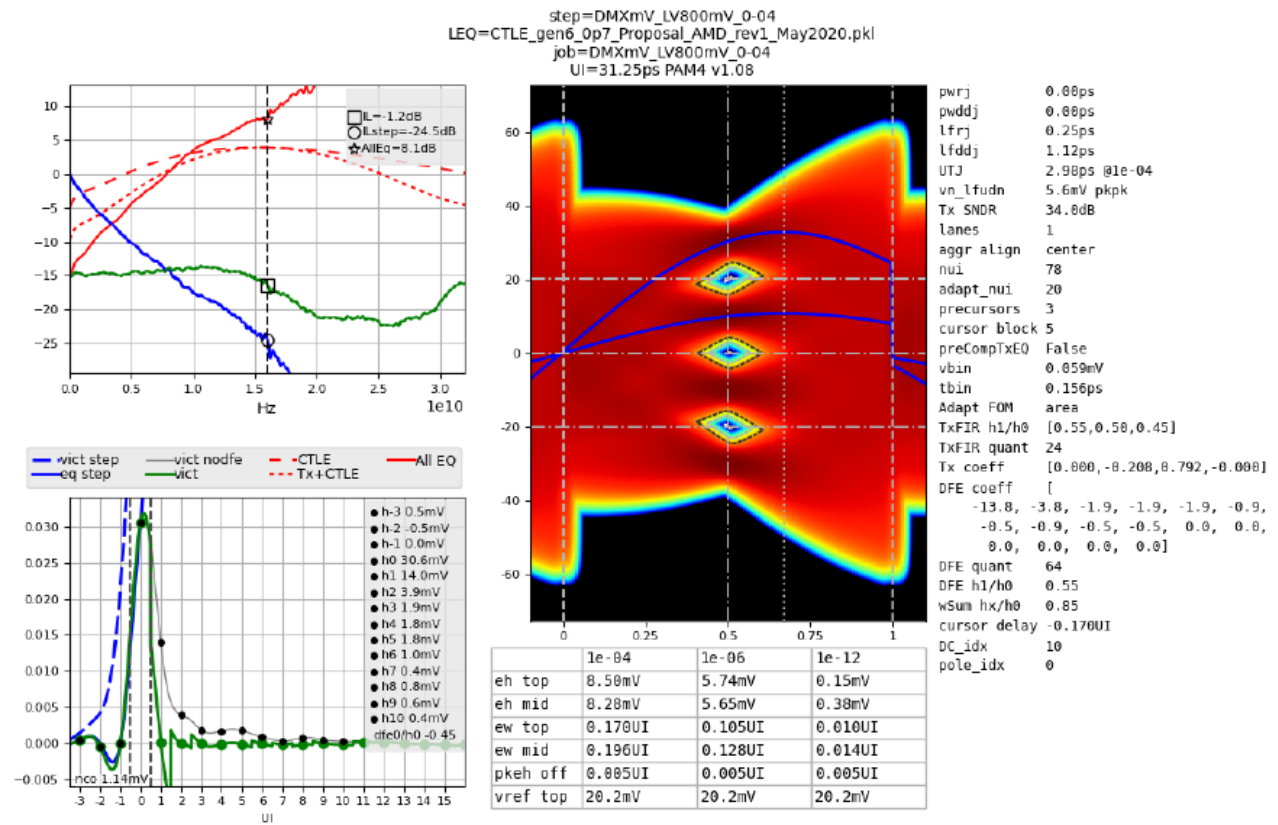


FIGURE 42. CALIBRATION RESULTS EXAMPLE

## 7 Saving and Loading Test Sessions

The GRL-PXE6-BASE-RXA software enables calibration and test results to be created and maintained as a 'Live Session' in the application. This allows the user to quit the application and return later to continue where the user left off.

Save and Load Sessions are used to save a test Session that the user may want to recall later. The user can 'switch' between different sessions by saving and loading them when needed.

- To save a session, with all of the parameter information, the test results, and any waveforms, select the "Options" drop-down menu, then the "Save Session" option.
- To load a session back into the software, including the saved parameter settings, select the "Options" drop-down menu, then the "Load Session" option.
- To create a New session and return the application back to a default configuration, select the "Options" drop-down menu, then the "New Session" option.

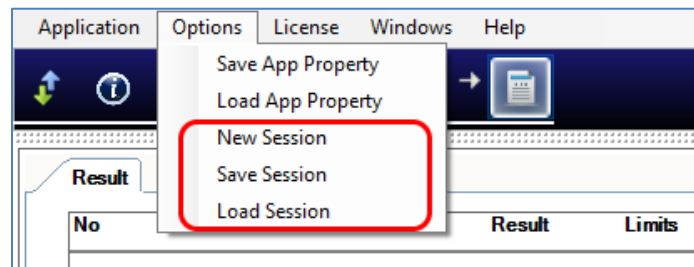


FIGURE 43. SAVING AND LOADING CALIBRATION AND TEST SESSIONS

The configuration and session results are saved in a file with the extension '.ses', which is a compressed zip-style file, containing a variety of information.

## 8 Appendix A: Method of Implementation (MOI) Using Automation

This section provides sample methodology to automate PCIe 6.0 Base Rx calibration using GRL-PXE6-BASE-RXA software at 64.0 GT/s. This procedure will ensure Receiver Impairment adjustments on the MP1900A BERT are accurate before running DUT compliance tests.

### 8.1 Perform Calibration at TP1

#### 8.1.1 Pre-shoot Calibration

The **Caltable** method is used to calibrate pre-shoot:

1. Set 800mV (p-p) amplitude on BERT.
2. Set 0dB for De-emphasis on BERT.
3. Measure:  
1dB at BERT, then measure Pre-shoot, record  
2dB at BERT, measure again, record  
3dB at BERT, measure again, record  
.....  
5dB at BERT, measure again, record.
4. Plot a Caltable graph.
5. Passing criteria is to obtain measured Pre-shoot at 1dB Min and Max 4dB.

#### 8.1.2 De-emphasis Calibration

The Caltable method is used to calibrate De-emphasis:

1. Set 800mV (p-p) amplitude on BERT.
2. Set 0dB for Pre-shoot on BERT.
3. Measure:  
-8dB at BERT, then measure De-emphasis, record  
-7dB at BERT, measure again  
-6dB at BERT, measure again  
.....  
0dB.
4. Plot a Caltable graph.
5. Passing criteria is to obtain measured De-emphasis at -1dB Min and Max -6dB.

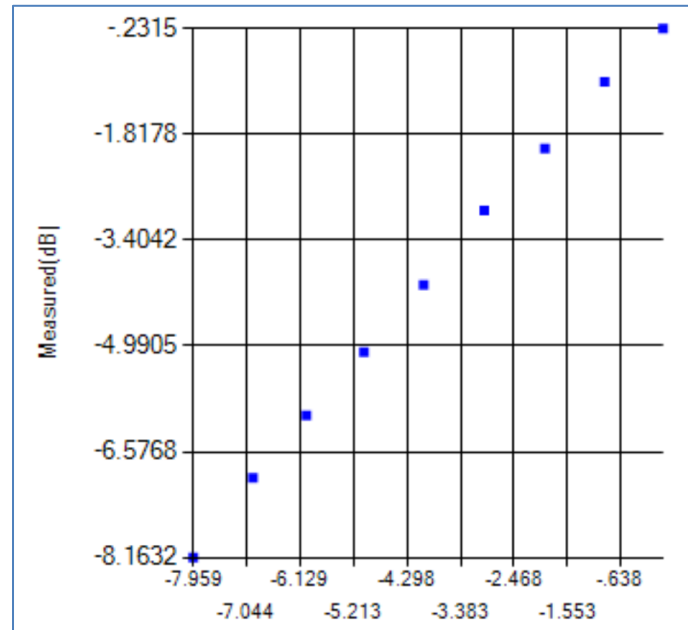


FIGURE 44. DE-EMPHASIS CALIBRATION CALTABLE GRAPH

### 8.1.3 Launch Amplitude Calibration

The Caltable method is used to calibrate Launch Amplitude:

1. Initialize BERT.
2. Set BERT to 0dB Pre-shoot and De-emphasis obtained from Caltable as measured above.
3. Set 300mV Amplitude at BERT, then measure the amplitude in scope, record it.
4. Increase 100mV on each iteration, measure the amplitude in scope, until measured amplitude meets or exceeds 1200mV.
5. Plot a Caltable graph.
6. Passing criteria is to obtain MEAN value of Launch Amplitude measurement at 720-800mV.

### 8.1.4 RJ Calibration

The Caltable method is used to calibrate RJ:

1. Initialize BERT.
2. Set 800mV (p-p) amplitude (based on calibrated value).
3. Set BERT to 0dB Pre-shoot and De-emphasis obtained from Caltable as measured above.
4. Set All Stress to 0mV.
5. Set 1100 Pattern on BERT.
6. Set Initial RJ value to 0.04UI(p-p) on BERT.
7. Measure RJ (in ps (RMS)) from scope using EZJIT, record the measured value.
8. Increase 0.1UI (p-p) on each iteration, measure RJ from scope, until measured RJ meets or exceeds 1.0ps (RMS).
9. Plot a Caltable graph.
10. Passing criteria is to obtain measured RJ at 1.0 ps (RMS).

### 8.1.5 SJ Calibration

The Caltable method is used to calibrate SJ:

1. Initialize BERT.
2. Set 800mV (p-p) amplitude (based on calibrated value).
3. Set BERT to 0dB Pre-shoot and De-emphasis obtained from Caltable as measured above.
4. Set All Stress to 0mV.
5. Set 1100 Pattern on BERT.
6. Set the SJ Frequency of the first Permutation (33KHz, 1MHz, 10MHz, 100MHz).
7. Set 0 (%UI (p-p)) as base value in SJ, measure SJ (in ps (p-p)) from scope using EJZIT, record.
8. Increase 0.1UI (p-p) on each iteration for SJ Frequency 1MHz, 10MHz, 100MHz; Increase 0.2UI (p-p) on each iteration for SJ Frequency 33KHz.
9. Measure SJ from scope until measured SJ meets or exceeds 62.5ps for 33KHz SJ Frequency or 20.0ps for SJ Frequency 1MHz, 10MHz, 100MHz.
10. Plot a Caltable graph.
11. Passing criteria is to obtain measured SJ at Min 6ps (p-p) and Max 62.5ps (p-p) for 33KHz, 20.0ps (p-p) for 1MHz, 10MHz, 100MHz.
12. Proceed to next permutation.

### 8.1.6 SJ Tone Calibration

The Caltable method is used to calibrate SJ Tone:

1. Initialize BERT.
2. Set 800mV (p-p) amplitude (based on calibrated value).
3. Set BERT to 0dB Pre-shoot and De-emphasis obtained from Caltable as measured above.
4. Set All Stress to 0mV.
5. Set 1100 Pattern on BERT.
6. Set SJ2 Frequency (210MHz).
7. Set 0 (%UI (p-p)) as base value in SJ2, measure SJ (in ps (p-p)) from scope using EJZIT, record.
8. Increase 0.1UI (p-p) on each iteration.
9. Measure SJ from scope until measured SJ meets or exceeds 10ps (p-p).
10. Plot a Caltable graph.
11. Passing criteria is to obtain measured SJ at Min 5ps (p-p) and Max 10ps (p-p).

## 8.2 Perform Calibration at TP2

Calibration at TP2 can be performed for Downstream (for Host) or Upstream (for Device).

### 8.2.1 ISI Calibration (CEM Connector Channel + Replica Channel)

1. Initialize BERT.
2. Set 800mV (p-p) amplitude (based on calibrated value).
3. Set BERT to 0dB Pre-shoot and De-emphasis obtained from Caltable as measured above.
4. Set All Stress to 0mV.
5. Set Clk/256 Pattern on BERT.
6. Start with PCIe CEM Variable ISI board Lane 3.
7. Trigger waveform on scope to display waveform.
8. Save waveform as .dat file (Y only).
9. Convert saved waveform to Seasim-compatible waveform (step response) with X component (start from 0). Save to xxx\_vict.rfstep1. The \_vict.rfstep1 format consists of time[SPACE]Voltage\_level[New Line].
10. Create Seasim config file with predefined values for IL calculation.
11. Run Seasim with config file and step response.
12. Obtain .log file and .csv file from Seasim.
13. Record insertion loss at 16GHz in dB from .csv file. Check against upper and lower specification limits.
14. If insertion loss at 16GHz is above 30-33dB, decrease Lane number and repeat steps 7 to 13.
15. If insertion loss at 16GHz is below 33dB, increase Lane number and repeat steps 7 to 13.
16. Insertion loss (IL) profile curve will be generated to determine Lane number that corresponds to 30-33dB losses for use in next step of calibration.

### 8.2.2 Common Mode (CM) Sinusoidal Interference Calibration

The Caltable method is used to calibrate CM-SI:

1. Insert ISI trace at 32dB loss from previous calibration step.
2. Initialize BERT.
3. Set 0mV (p-p) amplitude.
4. Set BERT to 0dB Pre-shoot and De-emphasis obtained from Caltable as measured above.
5. Set All Stress to 0mV.
6. Set Frequency on BERT for Common Mode to 120MHz.
7. Set Output on BERT for Common Mode to 20mV, turn On Output.
8. Turn Off Output on BERT for Differential Mode.
9. Initialize scope.
10. Set up Func1 on scope to (Chan1 + Chan3)/2.
11. Measure Vp-p on Func1.
12. Record measured Phase.
13. Set 800mV (p-p) amplitude (based on calibrated value).
14. Set All Zero Pattern on BERT.
15. Set ISI % value based on above calibrated data.
16. Set BERT (Common Mode) to Sine Wave.
17. Measure Amplitude (in mV) from scope, record.

18. Increase 0.174dBm/20mV on each iteration, measure Amplitude from scope until measured value meets or exceeds 150mV.
19. Plot a Caltable graph.
20. Passing criteria is to obtain measured CM-SI at Min 100mV and Max 150mV.

### 8.2.3 Differential Mode (DM) Sinusoidal Interference Calibration

This calibration is to ensure that the waveform achieves the calibrated eye height.

The Caltable method is used to calibrate DM-SI:

1. Insert ISI trace at 32dB loss from calibration step of Section 8.2.1.
2. Initialize BERT.
3. Set 0mV (p-p) amplitude.
4. Set BERT to 0dB Pre-shoot and De-emphasis obtained from Caltable as measured above.
5. Set All Stress to 0mV.
6. Set Frequency on BERT for Differential Mode to 2.1GHz.
7. Set Output on BERT for Differential Mode to 10mV, turn On Output.
8. Turn Off Output on BERT for Common Mode.
9. Initialize scope.
10. Set up Func1 on scope to (Chan1 – Chan3).
11. Measure Vp-p on Func1.
12. Measure Amplitude (in mV) from scope, record.
13. Increase 0.174dBm/10mV on each iteration, measure Amplitude from scope until measured value meets or exceeds 30mV.
14. Plot a Caltable graph.
15. Passing criteria is to obtain measured DM-SI at Min 10mV and Max 40mV.

### 8.2.4 Stress Jitter Voltage Eye Calibration

This calibration is to ensure that the waveform achieves the calibrated eye width and eye height.

1. Initialize BERT.
2. Set 800mV (p-p) amplitude (based on calibrated value).
3. Set All Stress to 0mV.
4. Set Clk/256 Pattern on BERT.
5. Start with ISI traces of 33dB.
6. Trigger waveform on scope to display waveform.
7. Embed waveform with reference package s4p.
8. Save waveform to .dat file (Y only).
9. Convert saved waveform to Seasim-compatible waveform (step response) with X component (starting from 5). Save to xxx\_vict.rfstep1. The \_vict.rfstep1 format consists of time[SPACE]Voltage\_level[New Line].
10. Create Seasim config file with predefined values for Eye Opening calculation, starting with 0mV DM-SI.
11. Run Seasim with config file and step response.
12. Obtain .log file from Seasim.
13. Read eye height (EH) and eye width (EW).
14. Record EH vs. DM, and EW vs. DM for 800mV.
15. Increase DM-SI (in Seasim config) to 6mV, run Seasim again, obtain EH and EW.

16. Once EH and EW at 6mV are obtained, plot Caltable graph and adjust DM setting needed to achieve 0.1UI and 6mV EH and EW.
17. If adjusted DM setting is out of range, increase/decrease SJ by 0.05UI. Repeat method to obtain EH and EW by adjusting DM.
18. If EH and EW do not fall within 6mV (top eye height:  $6\text{mV} \pm 0.5\text{mV}$ ) and 0.1UI (top eye width:  $3.125\text{ps} \pm 0.3\text{ps}$ ) respectively after SJ variation, reduce ISI by 0.5dB up to 30dB and repeat steps 15 to 17.
19. If EH and EW still do not fall within specifications, return to starting ISI trace of 33dB while adjusting Amplitude and reducing ISI if necessary.
20. Repeat until EW and EW fall within specifications.
21. Record measured Amplitude, SJ, and DM.

## 9 Appendix B: Connecting Keysight Oscilloscope to PC

If using a Keysight oscilloscope, refer to the following procedure on how to connect the Scope to be used with a PC. The Keysight Scope can be connected to the PC through GPIB, USB, or LAN.

1. Download the latest version of the Keysight IO Libraries Suite software from the Keysight website and install on the PC.
2. When installed successfully, the IO icon (  ) will appear in the taskbar notification area of the PC.
3. Select the IO icon to launch the **Keysight Connection Expert**.
4. Click Rescan.

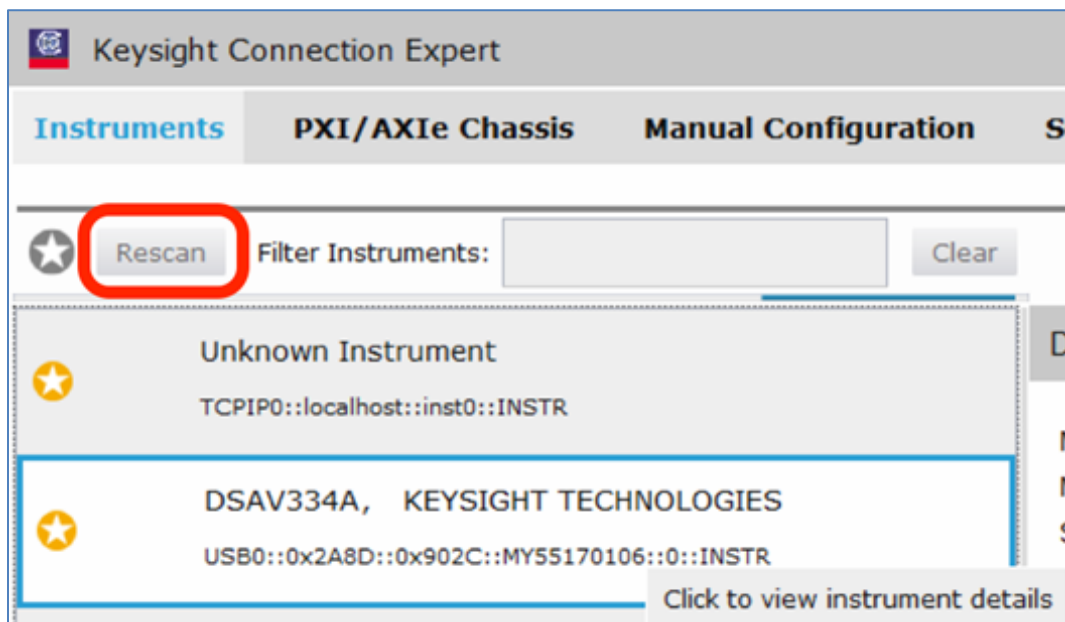


FIGURE 45. KEYSIGHT CONNECTION EXPERT

5. Refresh the system. The Keysight Scope is shown on the left pane and the VISA address is shown on the right pane.

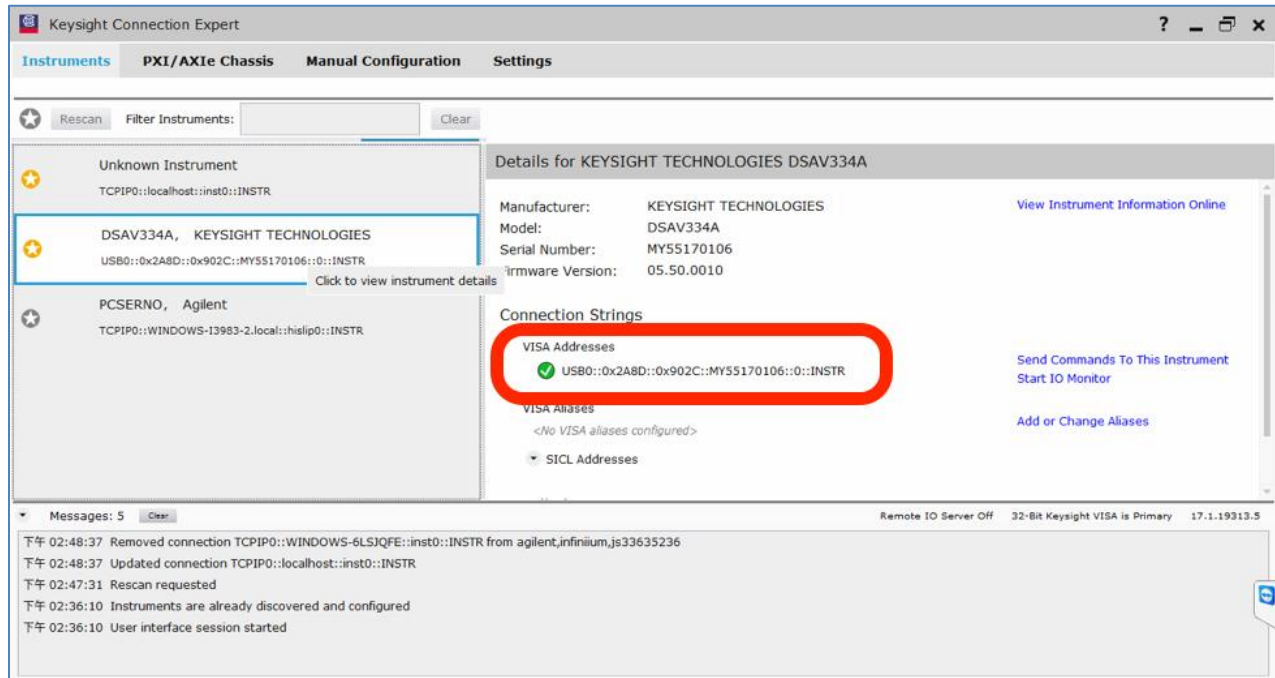


FIGURE 46. OSCILLOSCOPE'S VISA ADDRESS

6. When connecting the Keysight Scope to the PC through GPIB/USB, type in the VISA address into the 'Address' field on the Equipment Setup page of the GRL Platform Solutions PCIe 6.0 Base Rx Test Application. If connected via LAN, type in the Scope IP address, for example "TCPIP0::192.168.0.110::inst0::INSTR". Note to **omit** the Port number from the address.

If there is error in connection, type in the Scope IP address as "TCPIP0::192.168.0.4::5025::SOCKET".

## 10 Appendix C: Connecting Tektronix Oscilloscope to PC

If using a Tektronix DPOJET Series oscilloscope, refer to the following procedure on how to connect the Scope to be used with a PC. The Tektronix Scope can be connected to the PC through GPIB, USB, or LAN.

1. Download the latest version of the Tektronix TekVISA software from the Tektronix website and install on the PC.
2. When installed successfully, open the OpenChoice Instrument Manager application.

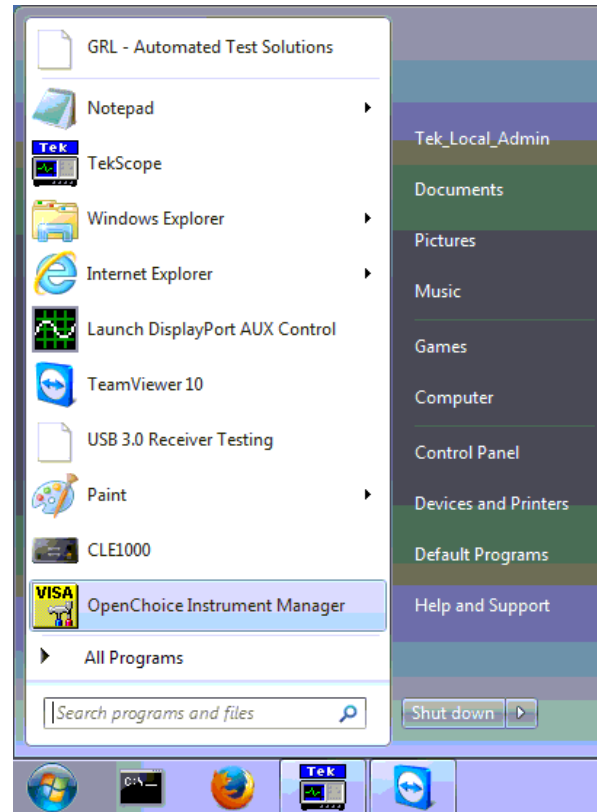


FIGURE 47. OPENCHOICE INSTRUMENT MANAGER IN START MENU

3. The left “Instruments” panel on the OpenChoice Instrument Manager will display all connected instruments. The functional buttons below the “Instruments” panel – “Instrument List Update”, “Search Criteria”, “Instrument Identify” and “Properties” can be used to detect the Scope in case it does not initially appear under “Instruments”.
  - a) “Instrument List Update”: Select to refresh the instrument list and locate new instruments connected to the PC.
  - b) “Search Criteria”: Select to configure the instrument search function.
  - c) “Instrument Identify”: Select to use a supported programming language to send a query to identify the selected instrument.
  - d) “Properties”: Select to display and view the selected instrument properties.

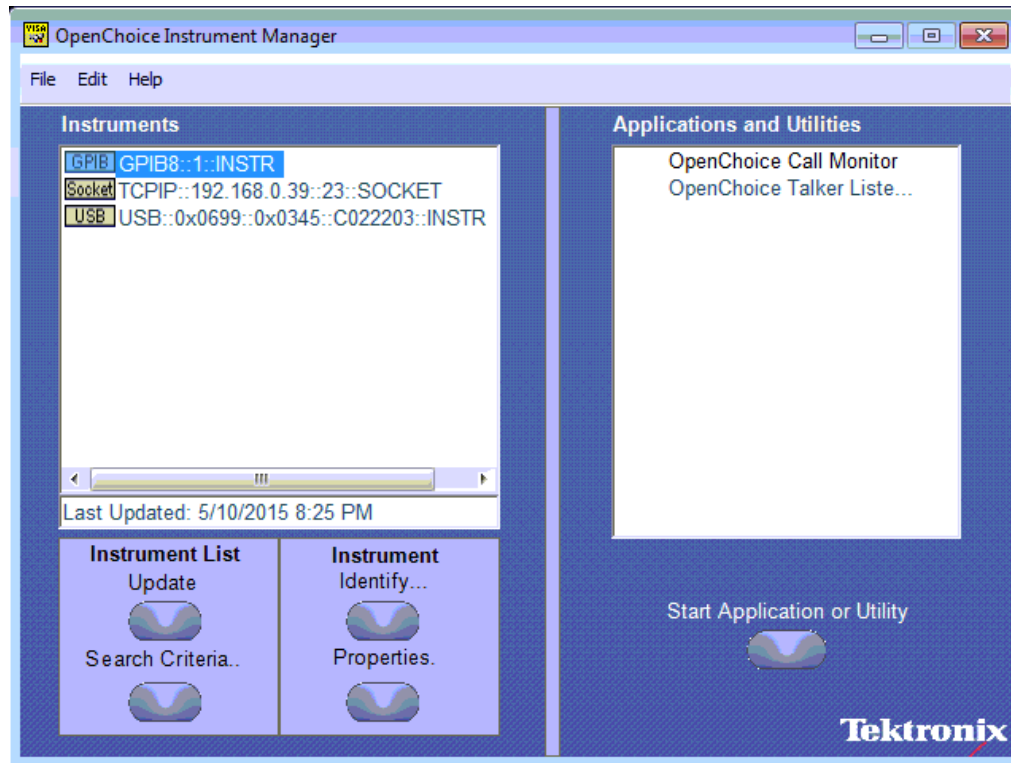


FIGURE 48. OPENCHOICE INSTRUMENT MANAGER MENU

4. If connecting the Tektronix Scope to the PC via USB, select the “Search Criteria” function to ensure that USB connection is enabled, and then select the “Instrument List Update” function. When the Scope appears on the “Instruments” panel, select it and then go to the “Instrument Identify” function. This will display the model and serial number of the Scope once detected. Select the “Properties” function to view the Scope address.
5. If connecting the Tektronix Scope to the PC via LAN, the Scope IP address must be pre-determined beforehand. Then select the “Search Criteria” function to ensure that LAN connection is enabled and type in the Scope IP address. When the Scope shows up in the list, select it followed by “Search”. The Scope should then appear on the “Instruments” panel. Select it and access the “Instrument Identify” function to view the Scope model and serial number as well as the “Properties” function to view the Scope address.
6. On the Equipment Setup page of the GRL Platform Solutions PCIe 6.0 Base Rx Test Application, type in the Scope address into the ‘Address’ field. If the PCIe 6.0 Base Rx Test Application is installed on the Tektronix Scope, ensure the Scope is connected via GPIB and type in the GPIB network address, for example “GPIB8::1::INSTR”. If the GRL Platform Solutions software is installed on the PC to control the Scope, type in the Scope IP address, for example “TCPIP0::192.168.0.110::inst0::INSTR”. Note to **omit** the Port number from the address.

**END\_OF\_DOCUMENT**